

# Statistical inference of network structure

## Part 1

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*University of Bath*

Berlin, August 2017

Introductory text:

*“Bayesian stochastic blockmodeling”*, arXiv: 1705.10225

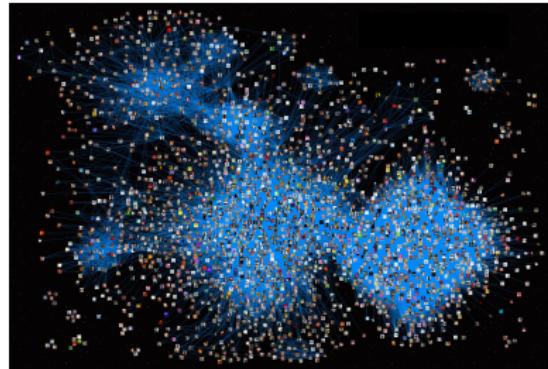
For code, see:

<https://graph-tool.skewed.de>

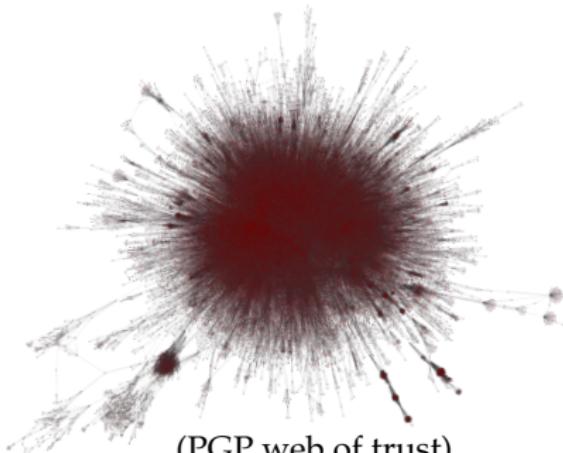
(See also HOWTO at: [https://graph-tool.skewed.de/  
static/doc/demos/inference/inference.html](https://graph-tool.skewed.de/static/doc/demos/inference/inference.html))

More infos at: <https://skewed.de/tiago>

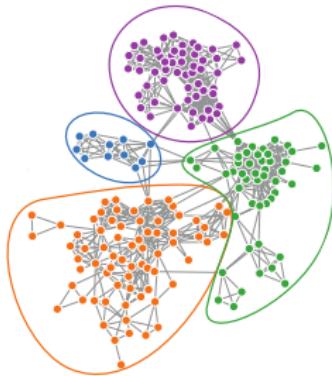
# HOW TO CHARACTERIZE LARGE-SCALE STRUCTURES?



(Flickr social network)



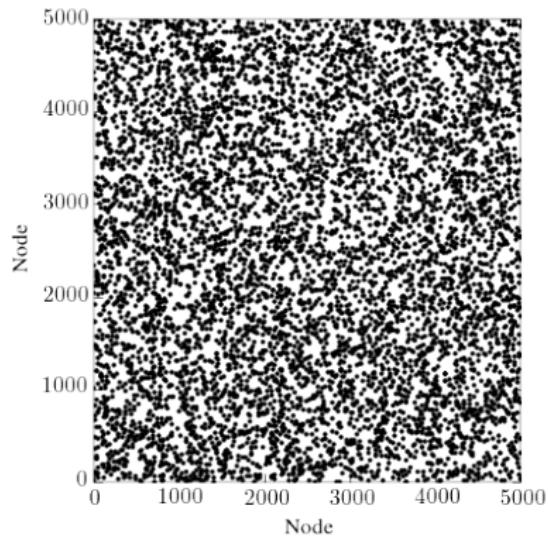
(PGP web of trust)



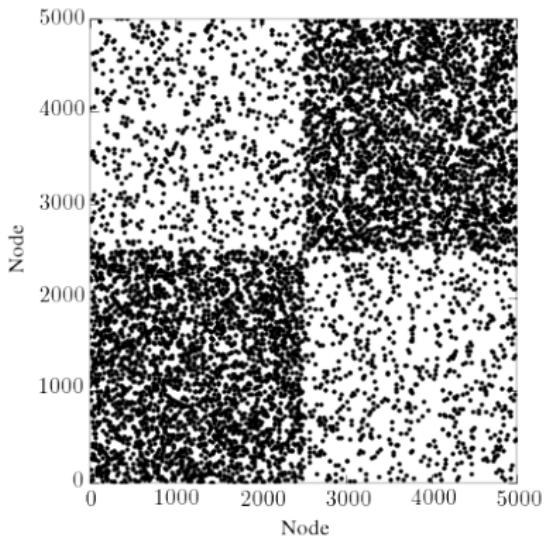
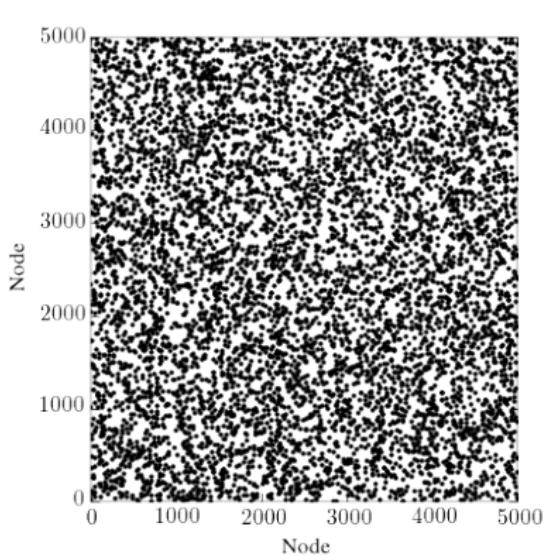
Find a meaningful network partition that provides:

- ▶ A division of nodes into groups that share similar properties.
- ▶ An understandable summary of the large-scale structure.
- ▶ An insight on function and evolution.

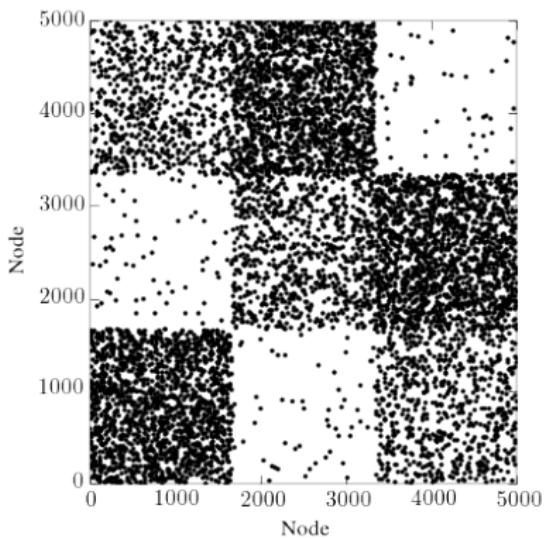
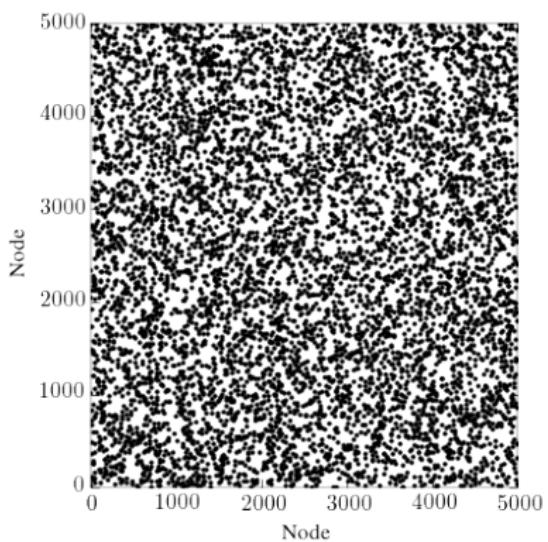
# STRUCTURE vs. RANDOMNESS



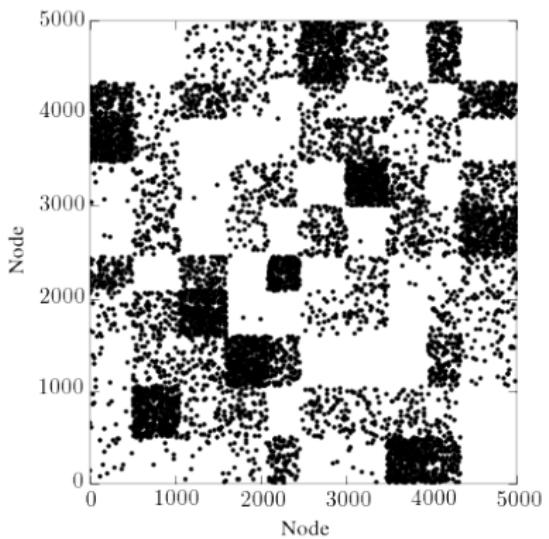
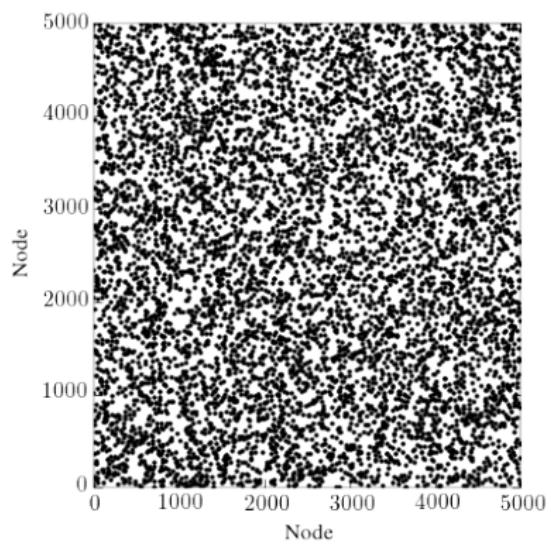
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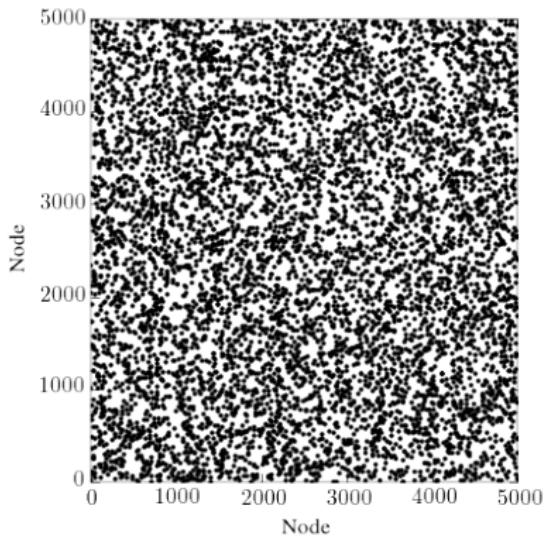
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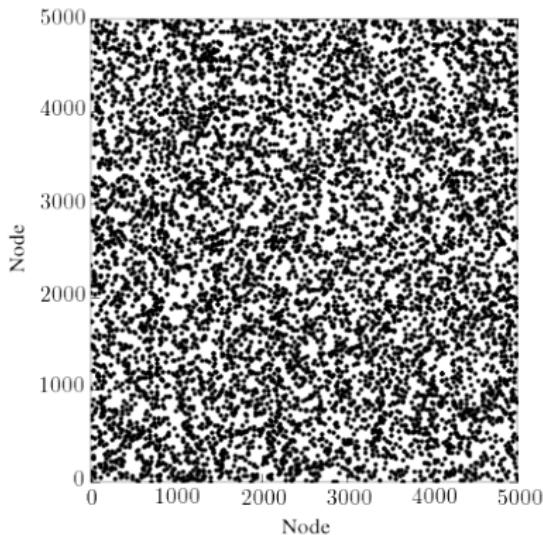
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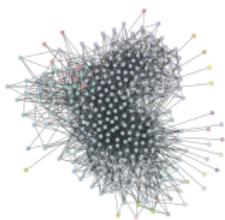
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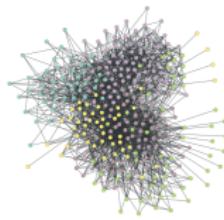
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We need *well defined, principled* methodology, grounded on robust concepts of **statistical inference**.

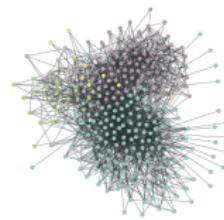
# DIFFERENT METHODS, DIFFERENT RESULTS...



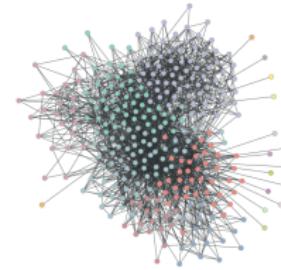
Betweenness



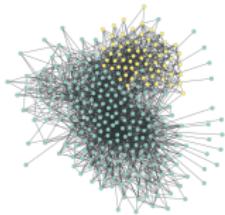
Modularity matrix



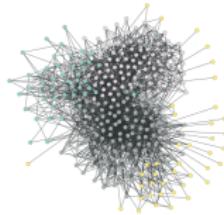
Infomap



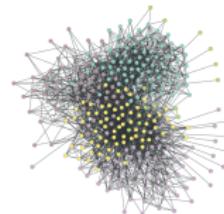
Walk Trap



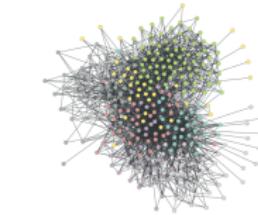
Label propagation



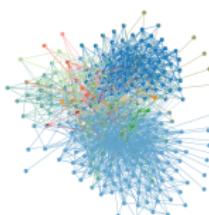
Modularity  
(Blondel)



Modularity  
(Blondel)



Spin glass



Infomap  
(overlapping)



Clique percolation

## A PRINCIPLED ALTERNATIVE: STATISTICAL INFERENCE

What we have:  $\mathbf{A} = \{A_{ij}\} \rightarrow$  Network

What we want:  $\mathbf{b} = \{b_i\}, b_i \in \{1, \dots, B\} \rightarrow$  Partition into groups

Generative model

$P(\mathbf{A}|\boldsymbol{\theta}, \mathbf{b}) \rightarrow$  Model likelihood

$\boldsymbol{\theta} \rightarrow$  Extra model parameters

Bayesian posterior

$$P(\mathbf{b}|\mathbf{A}) = \frac{P(\mathbf{A}|\mathbf{b})P(\mathbf{b})}{P(\mathbf{A})} \quad (\text{Bayes' rule})$$

$$P(\mathbf{A}|\mathbf{b}) = \int P(\mathbf{A}|\boldsymbol{\theta}, \mathbf{b})P(\boldsymbol{\theta}|\mathbf{b}) d\boldsymbol{\theta} \quad (\text{Marginal likelihood})$$

$$P(\boldsymbol{\theta}, \mathbf{b}) = P(\boldsymbol{\theta}|\mathbf{b})P(\mathbf{b}) \quad (\text{Prior probability})$$

$$P(\mathbf{A}) = \sum_{\mathbf{b}} P(\mathbf{A}|\mathbf{b})P(\mathbf{b}) \quad (\text{Evidence})$$

# WHY STATISTICAL INFERENCE?

$$P(\mathbf{b}|\mathbf{A}) = \frac{P(\mathbf{A}|\mathbf{b})P(\mathbf{b})}{P(\mathbf{A})} \quad (\text{Bayes' rule})$$
$$P(\mathbf{A}|\mathbf{b}) = \int P(\mathbf{A}|\boldsymbol{\theta}, \mathbf{b})P(\boldsymbol{\theta}|\mathbf{b}) d\boldsymbol{\theta}$$

## Nonparametric

- Dimension of the model (i.e. number of groups  $B$ ) can be inferred from data.
- Implements Occam's razor and prevents overfitting.

## Model selection

Different model classes,  $\mathcal{C}_1, \mathcal{C}_3, \mathcal{C}_3, \dots$

Posterior odds ratio:

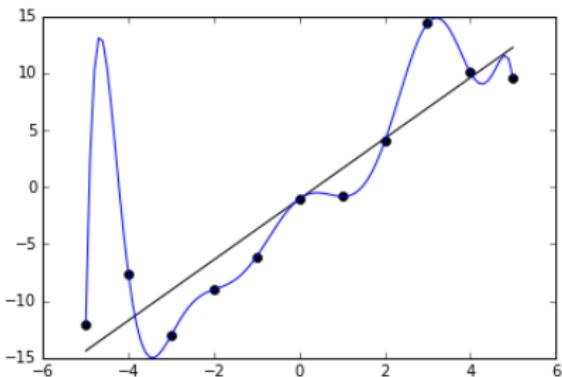
$$\Lambda = \frac{P(\mathbf{b}_1, \mathcal{C}_1 | \mathbf{A})}{P(\mathbf{b}_2, \mathcal{C}_2 | \mathbf{A})} = \frac{P(\mathbf{A}|\mathbf{b}_1, \mathcal{C}_1)P(\mathbf{b}_1)P(\mathcal{C}_1)}{P(\mathbf{A}|\mathbf{b}_2, \mathcal{C}_2)P(\mathbf{b}_2)P(\mathcal{C}_2)}$$

If  $\Lambda > 1$ ,  $(\mathbf{b}_1, \mathcal{C}_1)$  should be preferred over  $(\mathbf{b}_2, \mathcal{C}_2)$ .

# OVERFITTING, REGULARIZATION AND OCCAM'S RAZOR

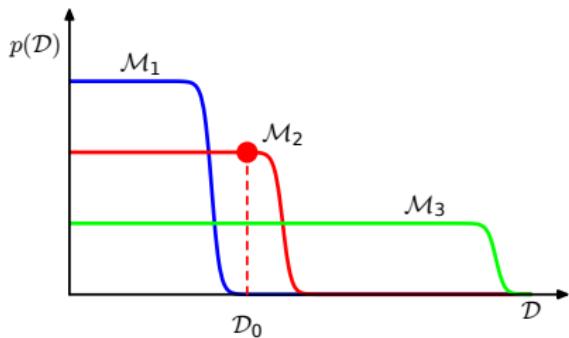
$$P(\boldsymbol{\theta}|\mathcal{D}) = \frac{P(\mathcal{D}|\boldsymbol{\theta})P(\boldsymbol{\theta})}{P(\mathcal{D})}$$

$\mathcal{D} \rightarrow \text{Data}, \boldsymbol{\theta} \rightarrow \text{Parameters}$



Evidence:

$$P(\mathcal{D}) = \int P(\mathcal{D}|\boldsymbol{\theta})P(\boldsymbol{\theta}) \, d\boldsymbol{\theta}$$



## TWO APPROACHES: PARAMETRIC VS. NON-PARAMETRIC

### Parametric

$$P(\mathbf{b}|\mathbf{A}, \boldsymbol{\theta}) = \frac{P(\mathbf{A}|\mathbf{b}, \boldsymbol{\theta})P(\mathbf{b})}{P(\mathbf{A}|\boldsymbol{\theta})}$$

$\boldsymbol{\theta} \rightarrow$  Remaining parameters are assumed to be known.

- ▶ Dimension of the model cannot be determined from data.
- ▶ Parameters  $\boldsymbol{\theta}$  are not typically known in practice.
- ▶ Problem has a simpler form, and becomes analytically tractable.
- ▶ Yields deeper understanding of the problem, and uncovers fundamental limits.

(Lenka Zdeborová's lectures.)

### Non-parametric

$$P(\mathbf{b}|\mathbf{A}) = \frac{P(\mathbf{A}|\mathbf{b})P(\mathbf{b})}{P(\mathbf{A})}$$

$$P(\mathbf{A}|\mathbf{b}) = \int P(\mathbf{A}|\boldsymbol{\theta}, \mathbf{b})P(\boldsymbol{\theta}|\mathbf{b}) \mathrm{d}\boldsymbol{\theta}$$

$\boldsymbol{\theta} \rightarrow$  Remaining parameters are unknown.

- ▶ Dimension of the model can be determined from data.
- ▶ Does not require knowledge of  $\boldsymbol{\theta}$ .
- ▶ Enables model selection, and prevents overfitting.
- ▶ Problem has a more complicated form, not amenable to the same tools used for the parametric case.

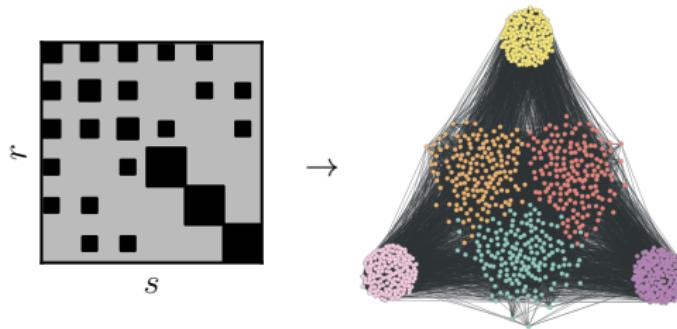
(Our focus.)

# THE STOCHASTIC BLOCK MODEL (SBM)

**Planted partition:**  $N$  nodes divided into  $B$  groups (blocks).

Parameters:  $b_i \rightarrow$  group membership of node  $i$

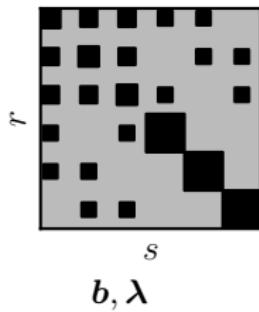
$\lambda_{rs} \rightarrow$  edge probability from group  $r$  to  $s$ .



- 
- ▶ Not restricted to assortative structures (“communities”).
  - ▶ Easily generalizable (edge direction, overlapping groups, etc.)

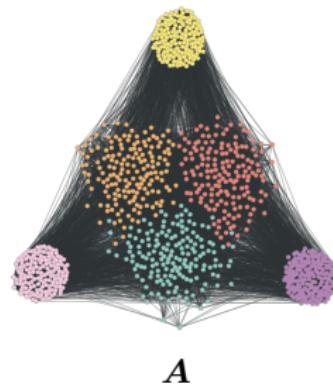
# BAYESIAN STATISTICAL INFERENCE

Network probability:  $P(\mathbf{A}|\boldsymbol{\lambda}, \mathbf{b})$



$$P(\mathbf{A}|\boldsymbol{\lambda}, \mathbf{b})$$

$\mathbf{A} \rightarrow$  Observed network  
 $\boldsymbol{\lambda}, \mathbf{b} \rightarrow$  Model parameters

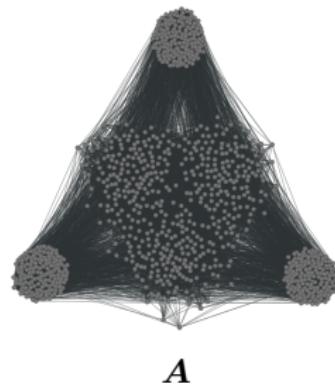


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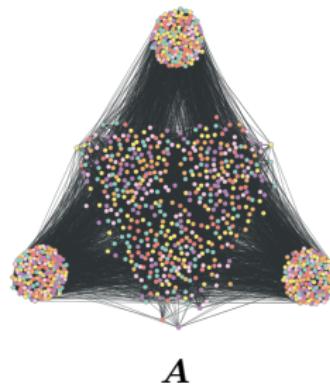


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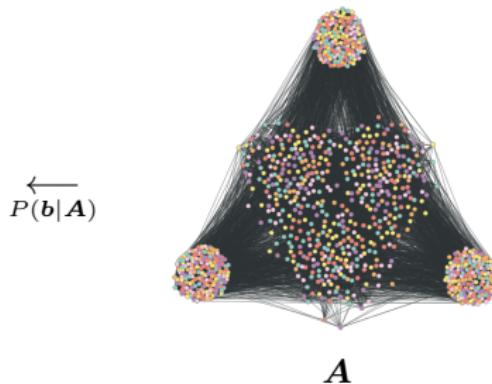


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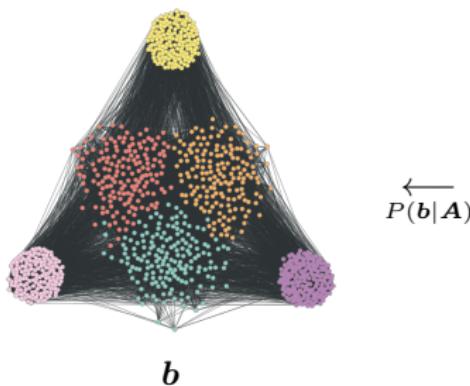


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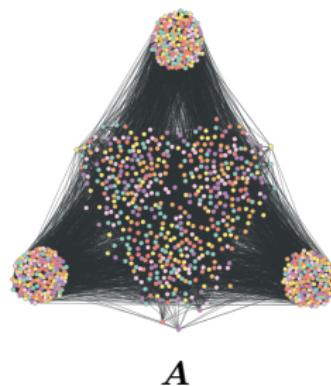
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$$P(\mathbf{b}|\mathbf{A})$$

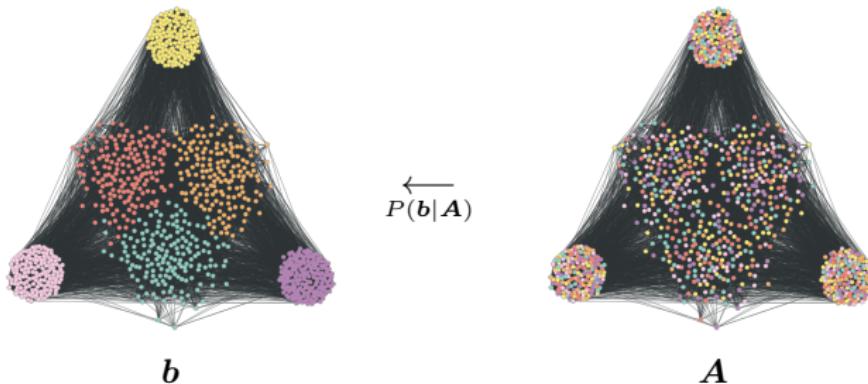


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# THE POISSON SBM

Model likelihood:

$$P(\mathbf{A}|\boldsymbol{\lambda}, \mathbf{b}) = \prod_{i < j} \frac{\lambda_{b_i b_j}^{A_{ij}} e^{-\lambda_{b_i b_j}}}{A_{ij}!} \times \prod_i \frac{(\lambda_{b_i b_i}/2)^{A_{ii}/2} e^{-\lambda_{b_i b_i}/2}}{(A_{ii}/2)!}$$

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Noninformative prior for  $\lambda$ :

$$P(\boldsymbol{\lambda}|\mathbf{b}) = \prod_{r < s} \frac{n_r n_s}{\bar{\lambda}} e^{-n_r n_s \lambda_{rs}/\bar{\lambda}} \times \prod_r \frac{n_r^2}{2\bar{\lambda}} e^{-n_r^2 \lambda_{rr}/2\bar{\lambda}}$$

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Marginal likelihood:

$$\begin{aligned} P(\mathbf{A}|\mathbf{b}) &= \int P(\mathbf{A}|\boldsymbol{\lambda}, \mathbf{b}) P(\boldsymbol{\lambda}|\mathbf{b}) d\boldsymbol{\lambda} \\ &= \frac{\bar{\lambda}^E}{(\bar{\lambda} + 1)^{E+B(B+1)/2}} \times \frac{\prod_{r < s} e_{rs}! \prod_r e_{rr}!!}{\prod_r n_r^{e_r} \prod_{i < j} A_{ij}! \prod_i A_{ii}!!} \end{aligned}$$

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Prior for  $\mathbf{b}$  (tentative):

$$P(\mathbf{b}|B) = \frac{1}{B^N}$$

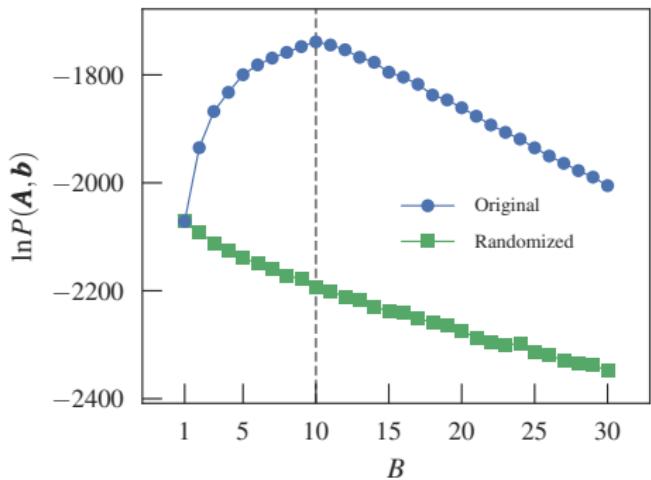
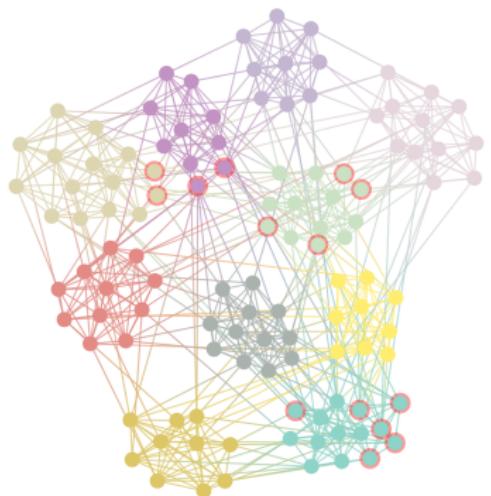
$$P(B) = 1/N$$

Posterior distribution:

$$P(\mathbf{b}|\mathbf{A}) = \frac{P(\mathbf{A}|\mathbf{b})P(\mathbf{b})}{P(\mathbf{A})}$$

$$P(\mathbf{A}) = \sum_{\mathbf{b}} P(\mathbf{A}|\mathbf{b})P(\mathbf{b})$$

# EXAMPLE: AMERICAN COLLEGE FOOTBALL TEAMS



## EXAMPLE: THE INTERNET MOVIE DATABASE (IMDB)

Bipartite network of actors and films.

Fairly large:  $N = 372,787$ ,  $E = 1,812,657$

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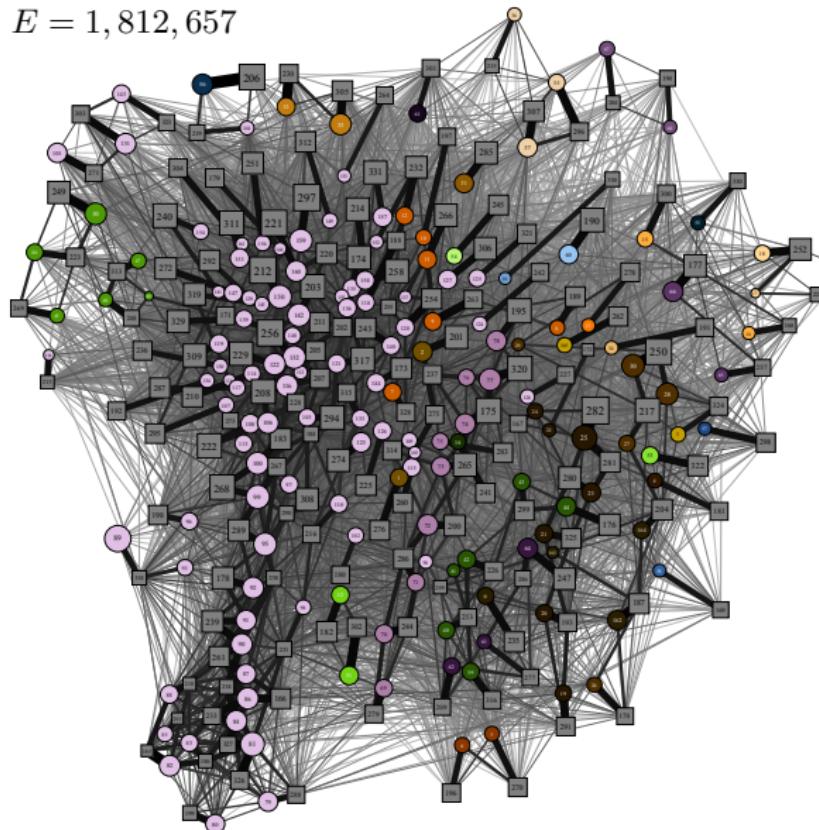
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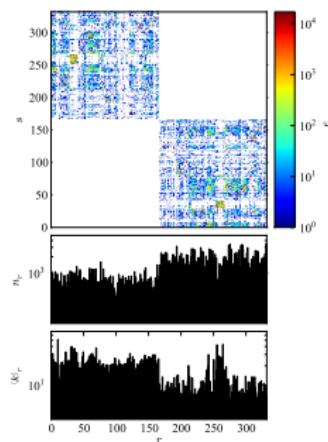


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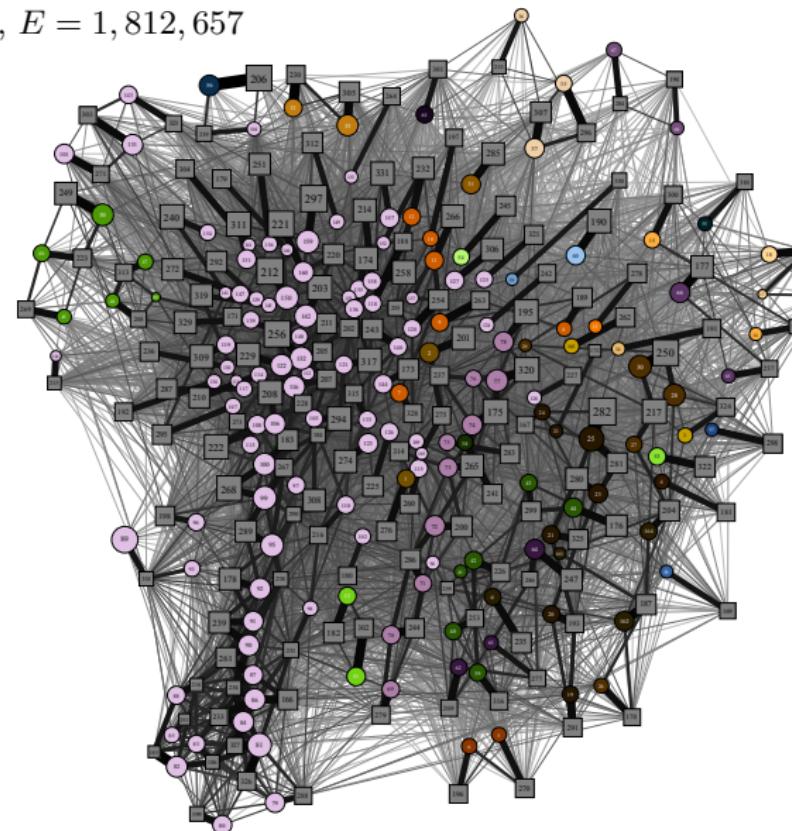
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Bipartiteness is fully uncovered!

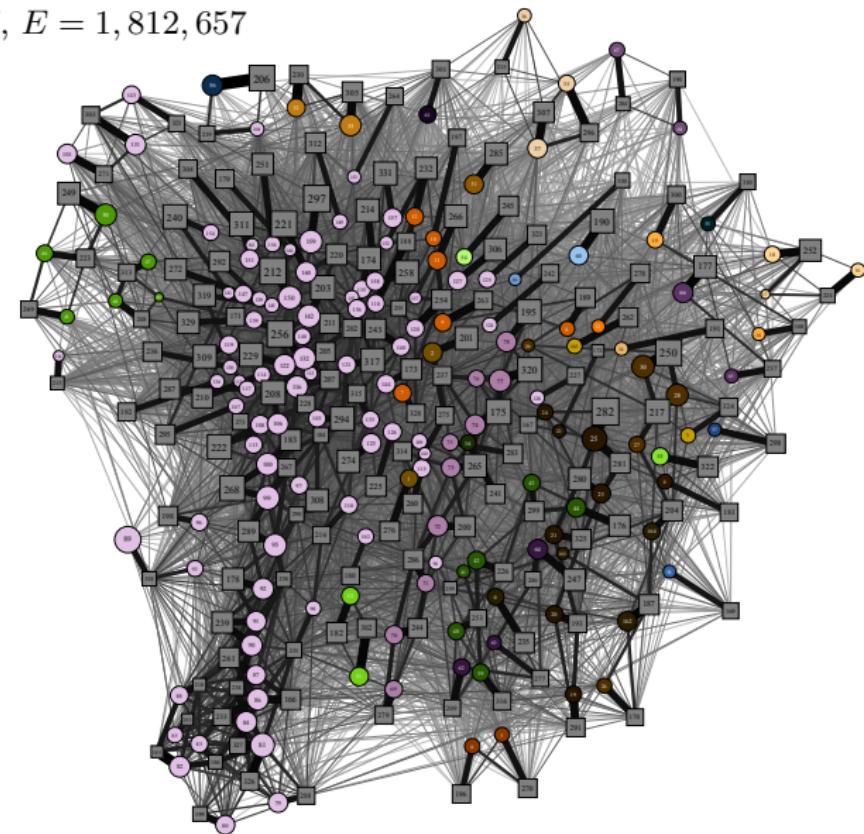
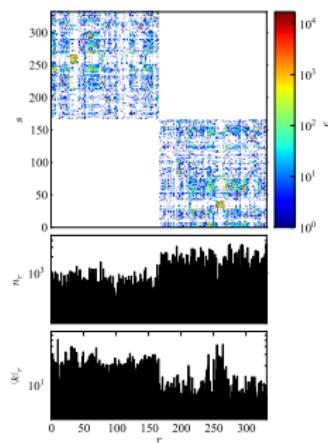


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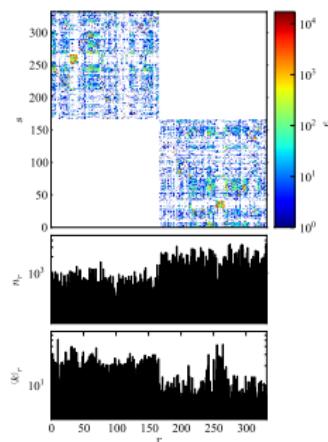
- ▶ Temporal
- ▶ Spatial (Country)
- ▶ Type/Genre

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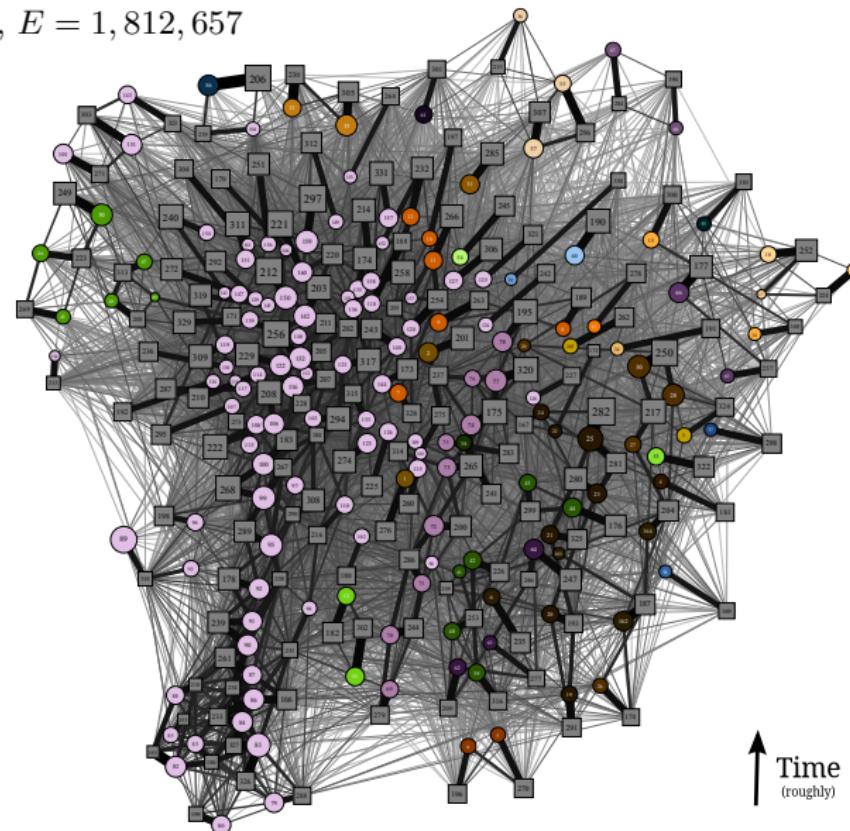
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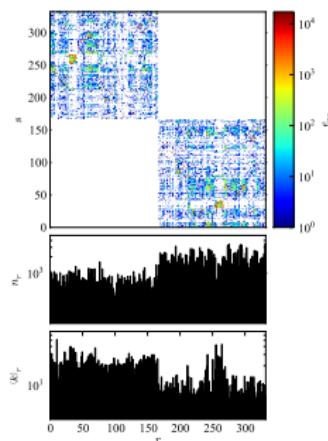


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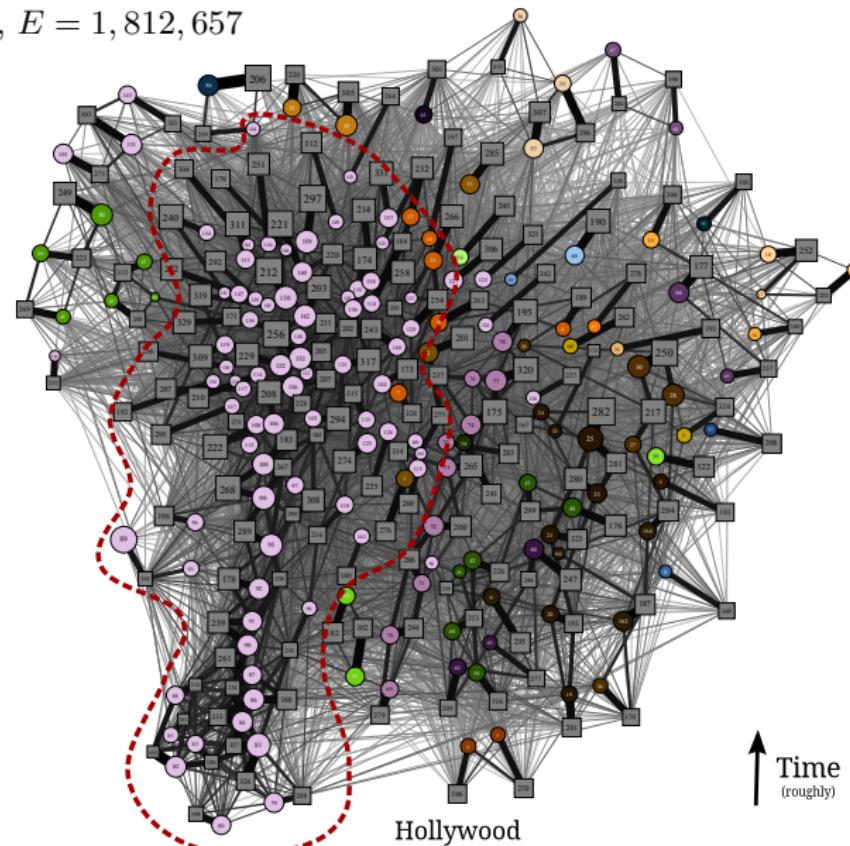
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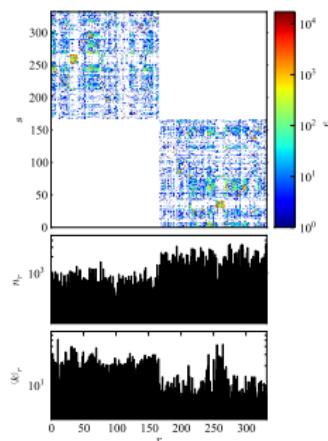


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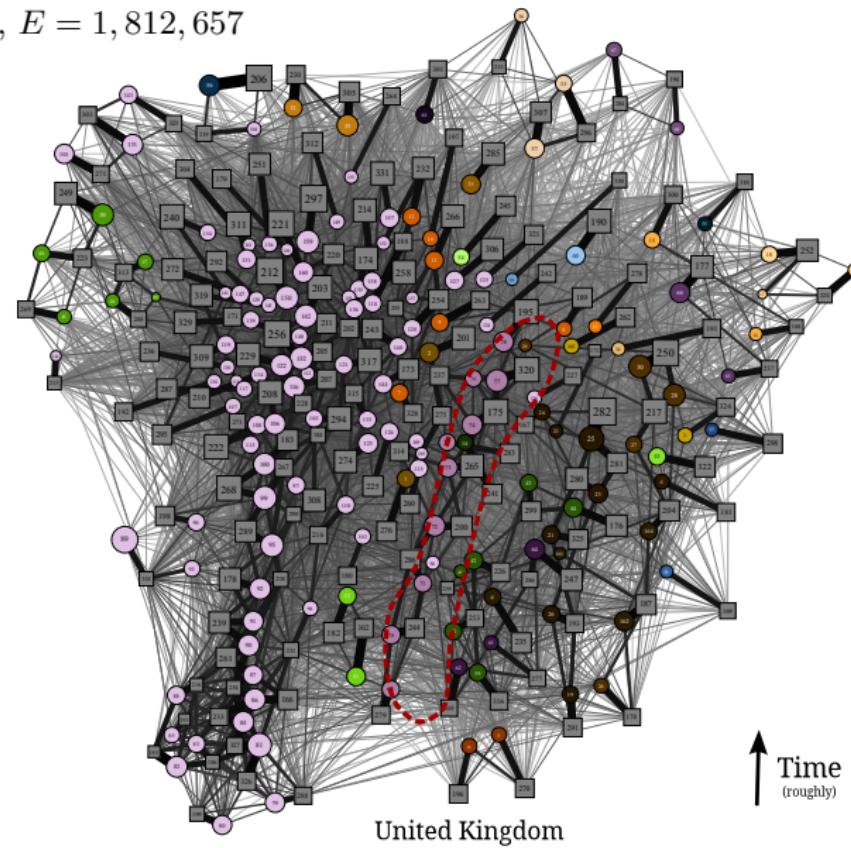
MDL selects:  $B = 332$



Bipartiteness is fully uncovered!

Meaningful features:

- ▶ Temporal
- ▶ Spatial (Country)
- ▶ Type/Genre

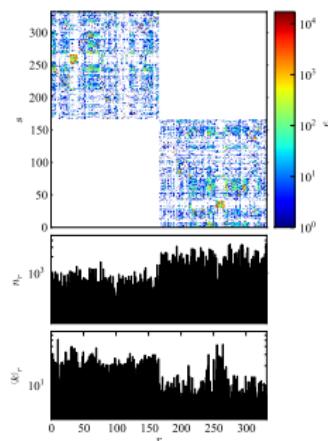


# EXAMPLE: THE INTERNET MOVIE DATABASE (IMDB)

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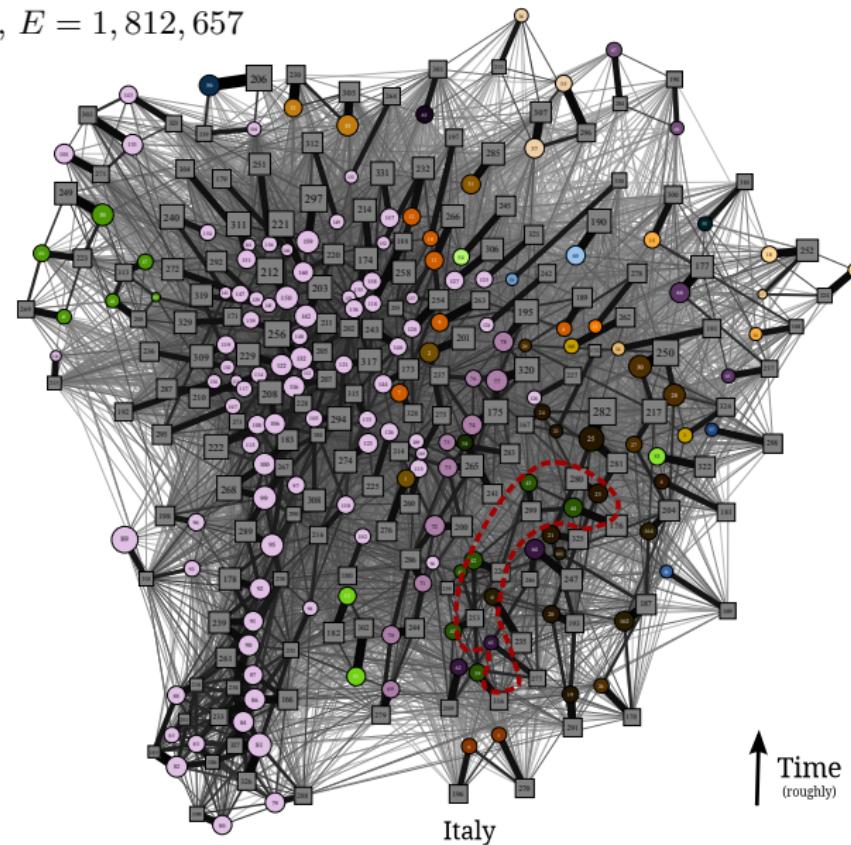
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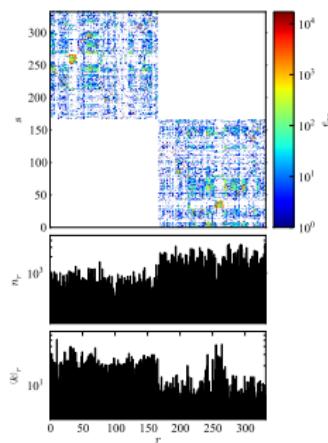


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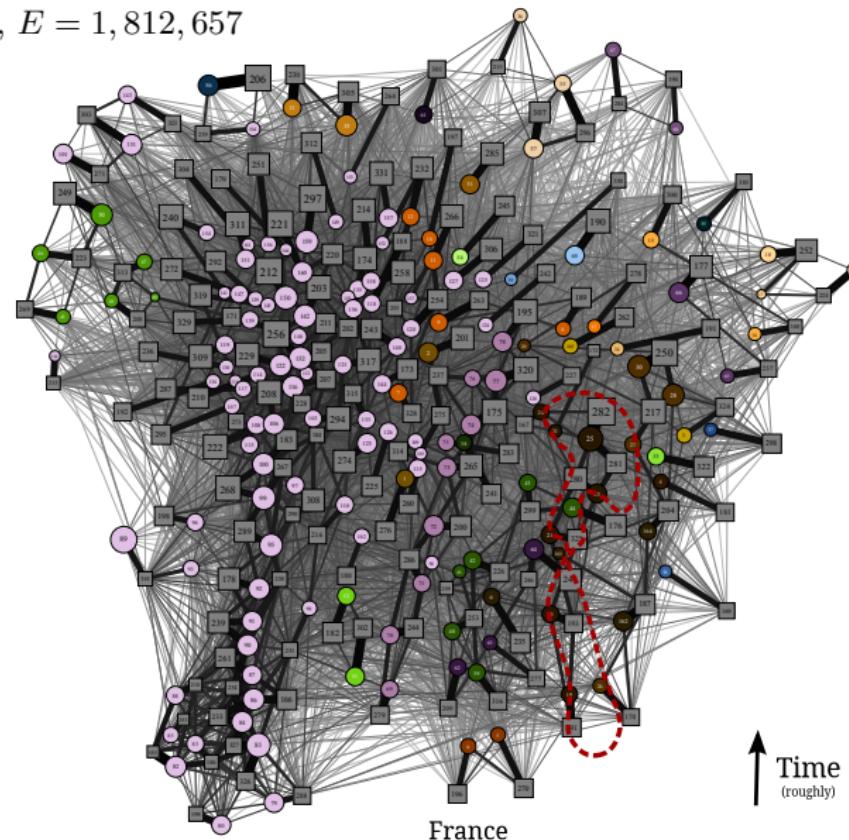
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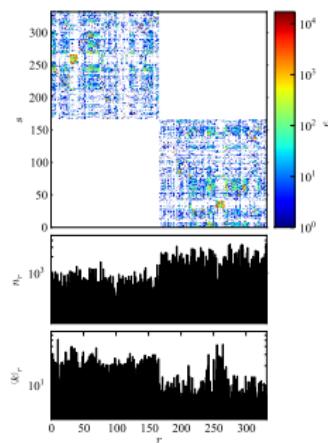


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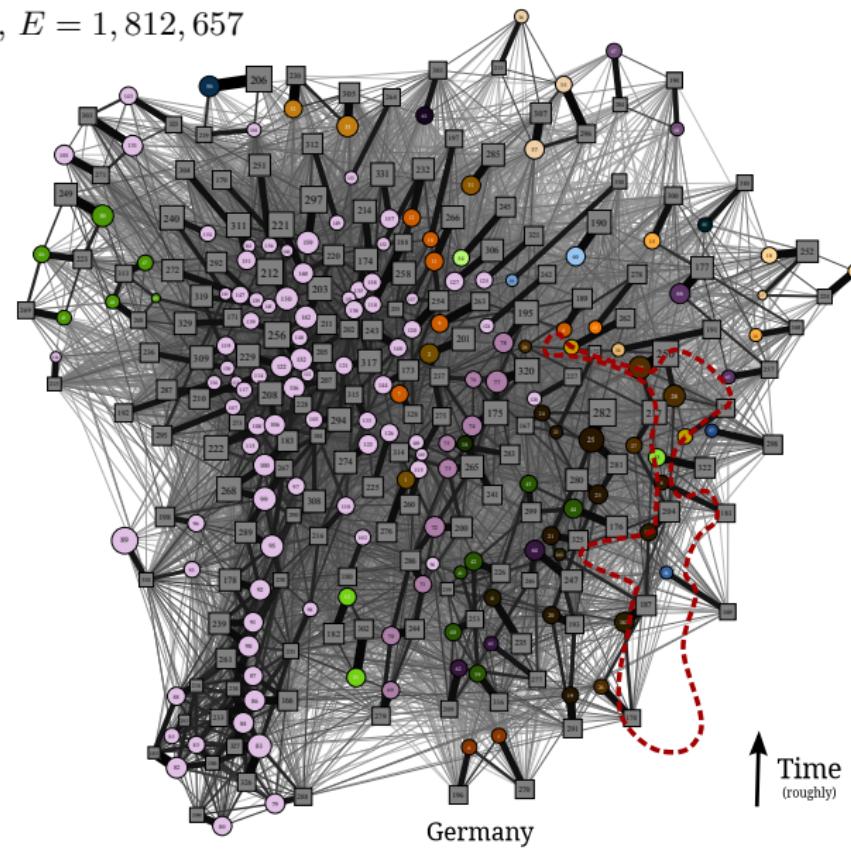
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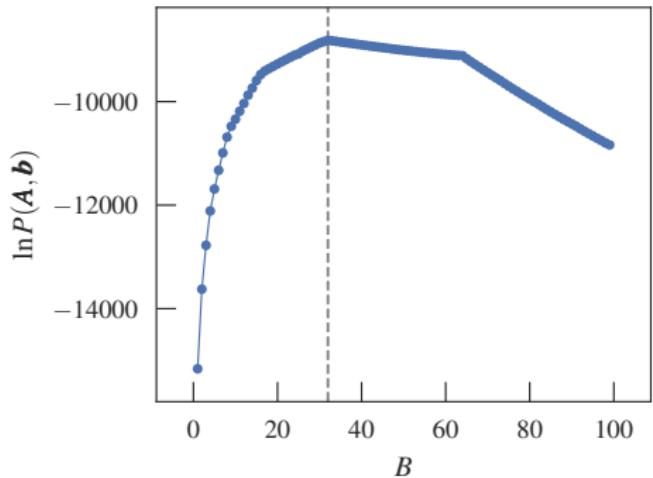
# UNDERFITTING: THE “RESOLUTION LIMIT” PROBLEM

64 cliques of size 10

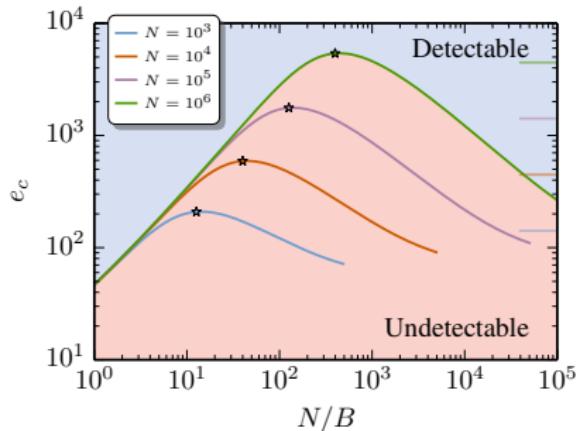
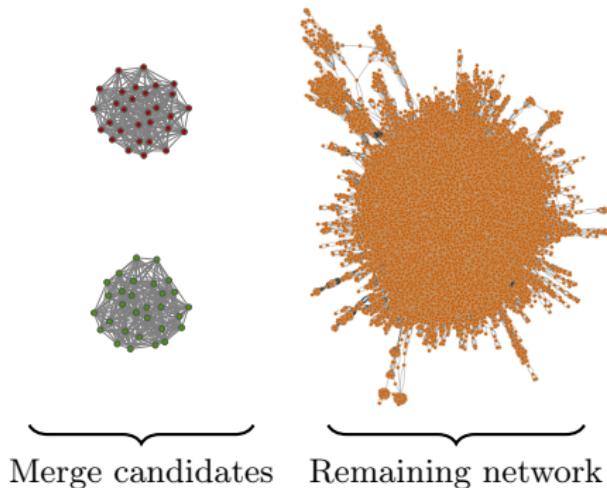


# UNDERFITTING: THE “RESOLUTION LIMIT” PROBLEM

64 cliques of size 10



# UNDERFITTING: THE “RESOLUTION LIMIT” PROBLEM



Minimum detectable block size  $\sim \sqrt{N}$ .

Why?

# MICROCANONICAL EQUIVALENCE

Marginal likelihood:

$$\begin{aligned} P(\mathbf{A}|\mathbf{b}) &= \int P(\mathbf{A}|\boldsymbol{\lambda}, \mathbf{b})P(\boldsymbol{\lambda}|\mathbf{b}) d\boldsymbol{\lambda} \\ &= \frac{\bar{\lambda}^E}{(\bar{\lambda} + 1)^{E+B(B+1)/2}} \times \frac{\prod_{r < s} e_{rs}! \prod_r e_{rr}!!}{\prod_r n_r^{e_r} \prod_{i < j} A_{ij}! \prod_i A_{ii}!!} \end{aligned}$$

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Equal to the joint probability of a **microcanonical** SBM:

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$$P(\mathbf{e}|\mathbf{b}) = \prod_{r < s} \frac{\bar{\lambda}^{e_{rs}}}{(\bar{\lambda} + 1)^{e_{rs}+1}} \prod_r \frac{\bar{\lambda}^{e_{rs}/2}}{(\bar{\lambda} + 1)^{e_{rs}/2+1}}$$

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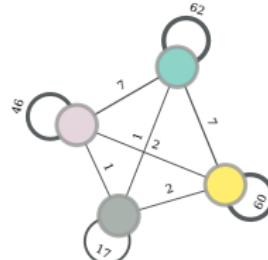
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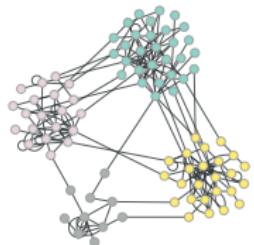
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Edge counts,  $\mathbf{e}$



Network,  $\mathbf{A}$

# MINIMUM DESCRIPTION LENGTH (MDL)

$$P(\mathbf{b}|\mathbf{A}) = \frac{P(\mathbf{A}, \mathbf{b})}{P(\mathbf{A})} = \frac{P(\mathbf{A}, \mathbf{e}, \mathbf{b})}{P(\mathbf{A})} = \frac{2^{-\Sigma}}{P(\mathbf{A})}$$

Description length:

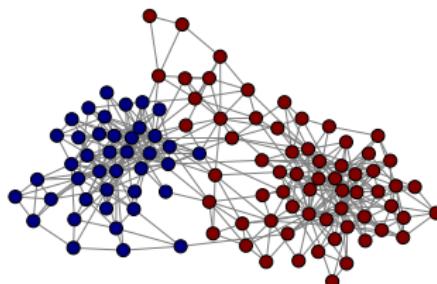
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$$B = 2, \mathcal{S} \approx 1805.3 \text{ bits}$$



$$\text{Model, } \mathcal{L} \approx 122.6 \text{ bits}$$

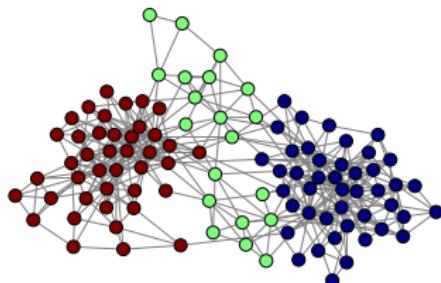
$$\Sigma \approx 1927.9 \text{ bits}$$

# MINIMUM DESCRIPTION LENGTH (MDL)

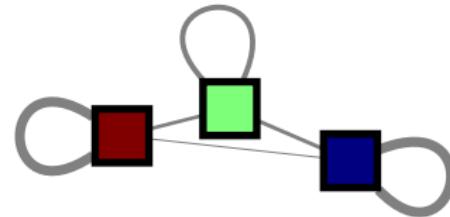
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$$B = 3, \mathcal{S} \approx 1688.1 \text{ bits}$$



$$\text{Model, } \mathcal{L} \approx 203.4 \text{ bits}$$

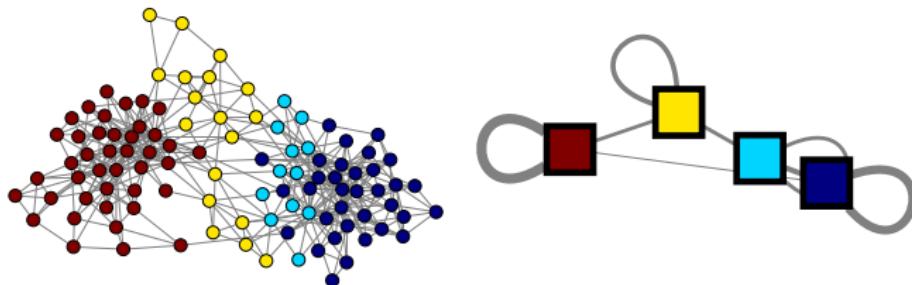
$$\Sigma \approx 1891.5 \text{ bits}$$

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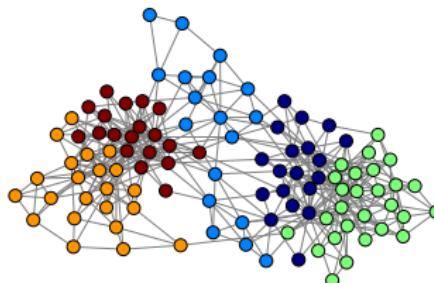


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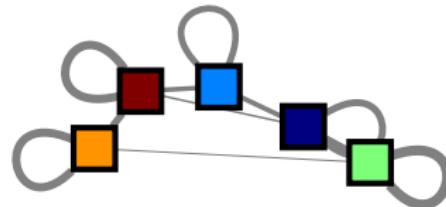
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$$B = 5, \mathcal{S} \approx 1590.5 \text{ bits}$$



$$\text{Model, } \mathcal{L} \approx 330.8 \text{ bits}$$

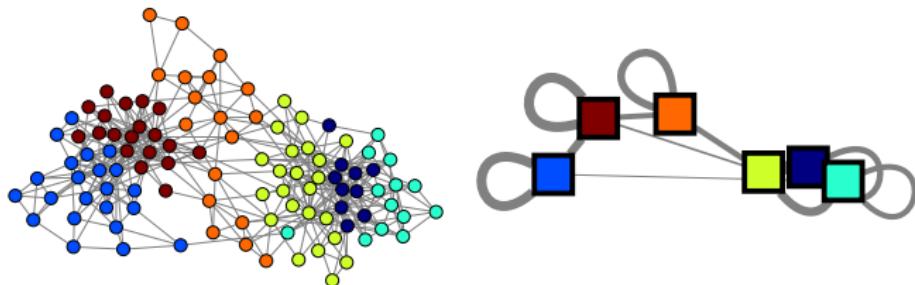
$$\Sigma \approx 1921.3 \text{ bits}$$

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$$B = 6, \mathcal{S} \approx 1554.2 \text{ bits}$$

$$\text{Model, } \mathcal{L} \approx 386.7 \text{ bits}$$

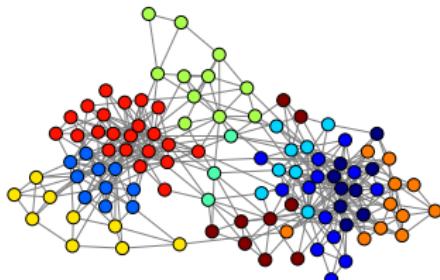
$$\Sigma \approx 1940.9 \text{ bits}$$

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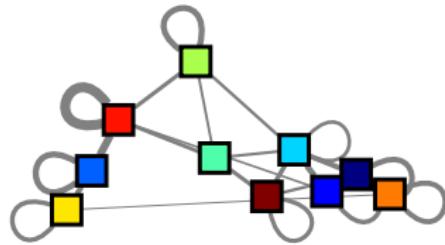
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$$B = 10, \mathcal{S} \approx 1451.0 \text{ bits}$$



$$\text{Model, } \mathcal{L} \approx 590.8 \text{ bits}$$

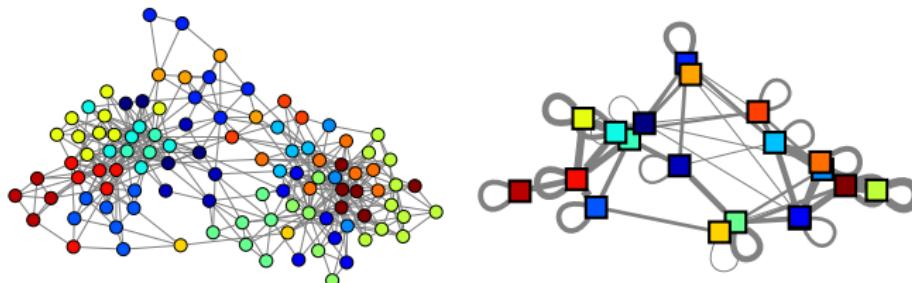
$$\Sigma \approx 2041.8 \text{ bits}$$

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$$B = 20, \mathcal{S} \approx 1300.7 \text{ bits}$$

$$\text{Model, } \mathcal{L} \approx 1037.8 \text{ bits}$$

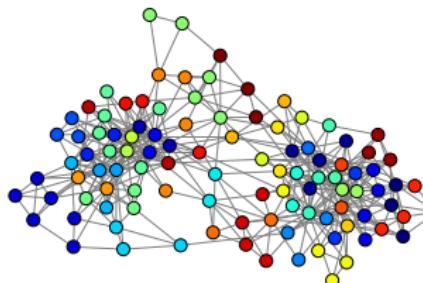
$$\Sigma \approx 2338.6 \text{ bits}$$

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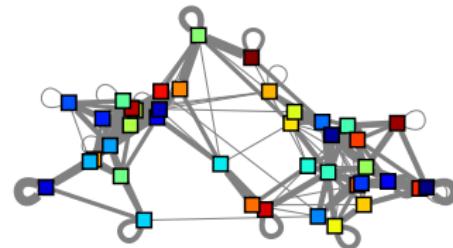
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$$B = 40, \mathcal{S} \approx 1092.8 \text{ bits}$$



$$\text{Model, } \mathcal{L} \approx 1730.3 \text{ bits}$$

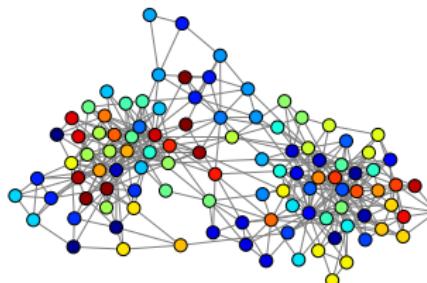
$$\Sigma \approx 2823.1 \text{ bits}$$

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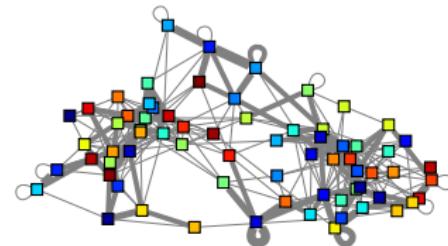
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$$B = 70, \mathcal{S} \approx 881.3 \text{ bits}$$



$$\text{Model, } \mathcal{L} \approx 2427.3 \text{ bits}$$

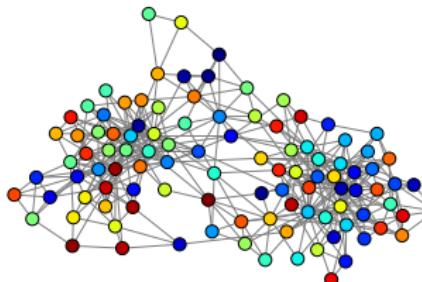
$$\Sigma \approx 3308.6 \text{ bits}$$

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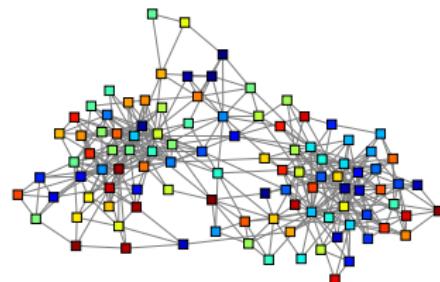
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$B = N, \mathcal{S} = 0$  bits



Model,  $\mathcal{L} \approx 3714.9$  bits

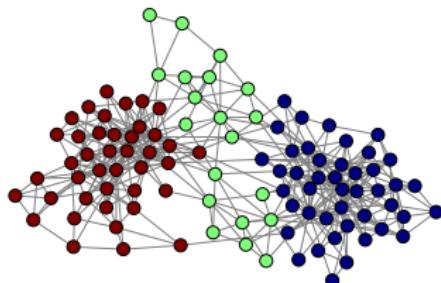
$\Sigma \approx 3714.9$  bits

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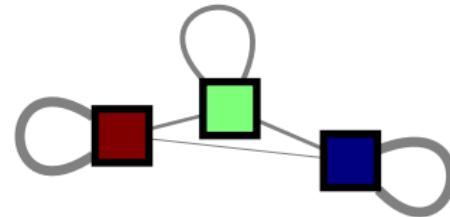
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$$B = 3, \mathcal{S} \approx 1688.1 \text{ bits}$$



$$\text{Model, } \mathcal{L} \approx 203.4 \text{ bits}$$

$$\Sigma \approx 1891.5 \text{ bits}$$

# NONINFORMATIVE PRIORS AND UNDERFITTING



$$\Sigma \approx -(E - N) \log_2 B + \frac{B(B + 1)}{2} \log_2 E$$

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“resolution limit”

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Q: How to do better *without* prior information?

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“resolution limit”

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Q: How to do better *without* prior information?

A: Construct a model for the model!

$$P(\mathbf{A}|\mathbf{b}) = \int P(\mathbf{A}|\boldsymbol{\lambda}, \mathbf{b}) P(\boldsymbol{\lambda}|\boldsymbol{\phi}) P(\boldsymbol{\phi}) d\boldsymbol{\lambda} d\boldsymbol{\phi}$$

# NONINFORMATIVE PRIORS AND UNDERFITTING



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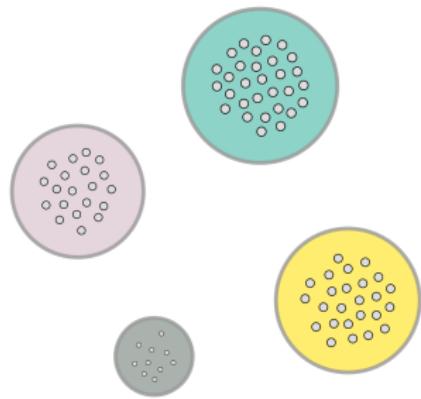
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Microcanonical:

$$P(\mathbf{A}|\mathbf{b}) = P(\mathbf{A}|\mathbf{e}, \mathbf{b}) P(\mathbf{e}|\boldsymbol{\psi}) P(\boldsymbol{\psi})$$

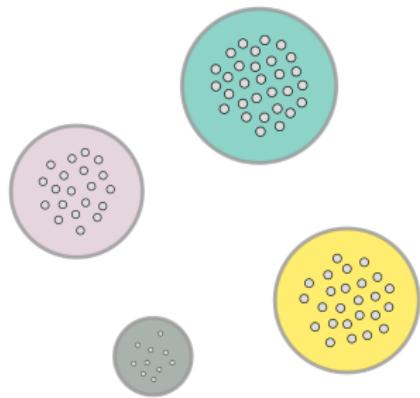
# PRIOR FOR THE PARTITION



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Option 1: Noninformative

$$P(\mathbf{b}) = \frac{1}{\sum_{B=1}^N \left\{ \begin{matrix} N \\ B \end{matrix} \right\} B!}$$



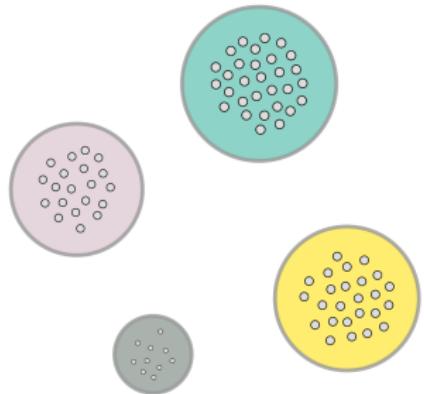
# PRIOR FOR THE PARTITION

Option 1: Noninformative

$$P(\mathbf{b}) = \frac{1}{\sum_{B=1}^N \left\{ \begin{smallmatrix} N \\ B \end{smallmatrix} \right\} B!}$$

Option 2: Slightly less noninformative

$$P(\mathbf{b}|B) = \frac{1}{\left\{ \begin{smallmatrix} N \\ B \end{smallmatrix} \right\} B!} \quad P(B) = \frac{1}{N}$$



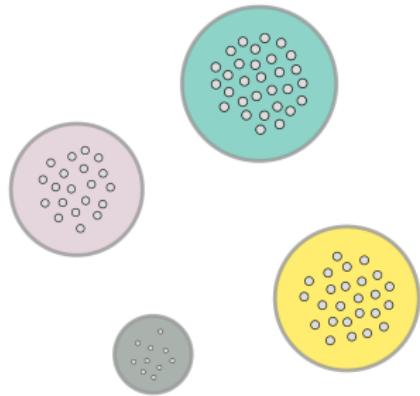
# PRIOR FOR THE PARTITION

Option 1: Noninformative

$$P(\mathbf{b}) = \frac{1}{\sum_{B=1}^N \left\{ \begin{matrix} N \\ B \end{matrix} \right\} B!}$$

Option 2: Slightly less noninformative

$$P(\mathbf{b}|B) = \frac{1}{\left\{ \begin{matrix} N \\ B \end{matrix} \right\} B!} \quad P(B) = \frac{1}{N}$$



Option 3: Conditioned on group sizes

$$\begin{aligned} P(\mathbf{b}|B) &= P(\mathbf{b}|\mathbf{n})P(\mathbf{n}) \\ &= \frac{N!}{\prod_r n_r!} \times \binom{N-1}{B-1}^{-1} \end{aligned}$$

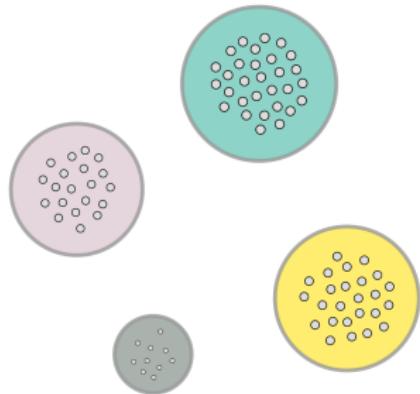
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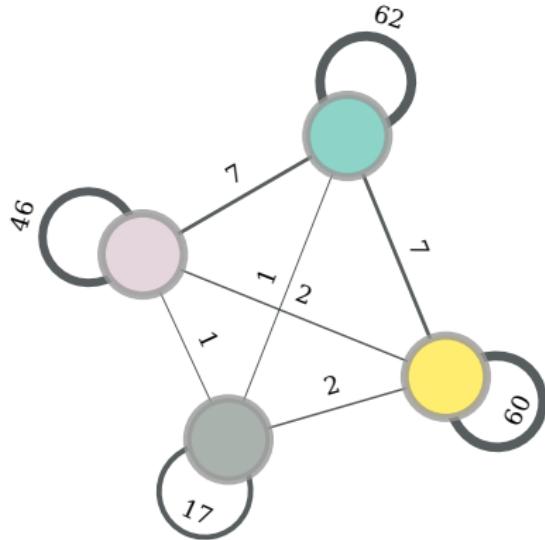
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For  $N \gg B$ :

$$-\ln P(\mathbf{b}|B) \approx NH(\mathbf{n}) + O(B \ln N)$$

$$H(\mathbf{n}) = - \sum_r \frac{n_r}{N} \ln \frac{n_r}{N}$$

# PRIOR FOR THE EDGE COUNTS



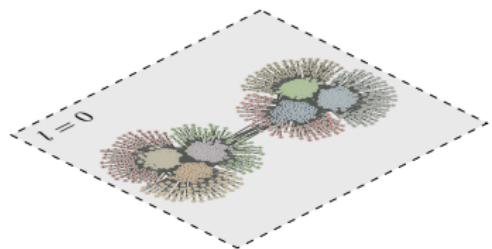
Option 1: Noninformative

$$P(\mathbf{e}) = \left( \binom{\binom{B}{2}}{E} \right)^{-1}$$

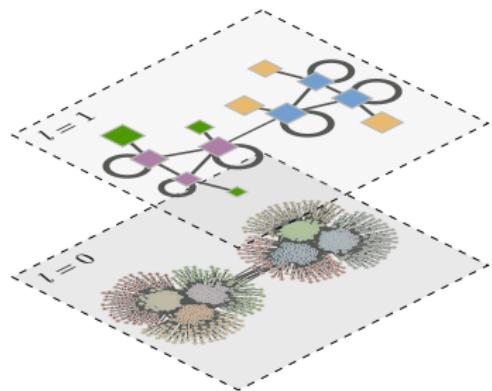
$$\binom{n}{m} = \binom{n+m-1}{m}$$

# NESTED SBM: GROUP HIERARCHIES

Condition  $P(e)$  on... another SBM!

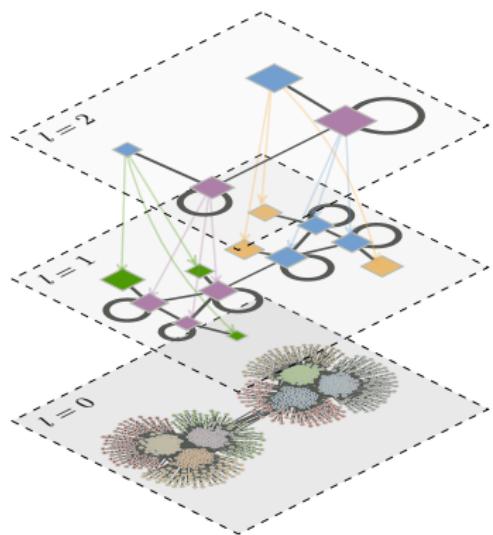


# NESTED SBM: GROUP HIERARCHIES



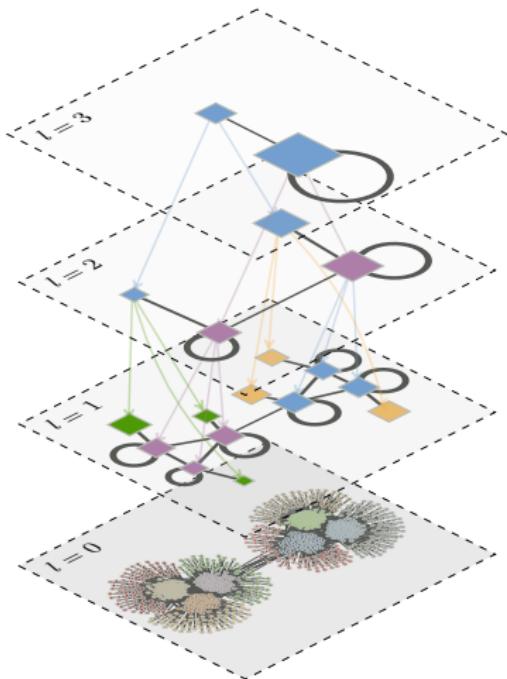
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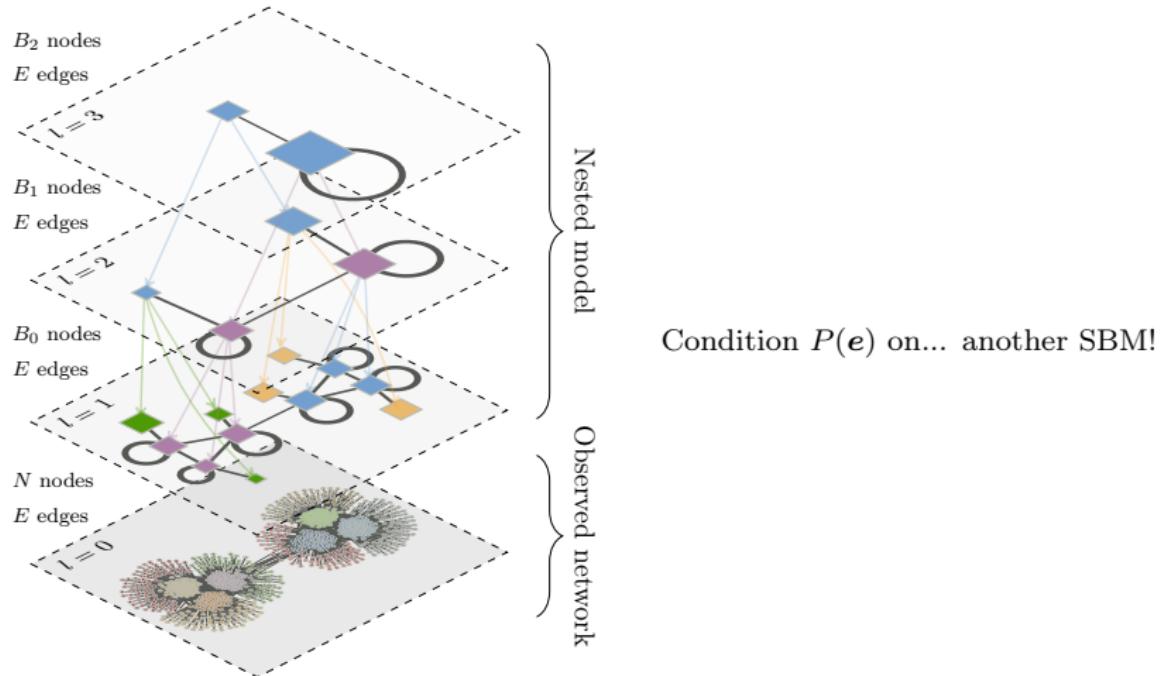
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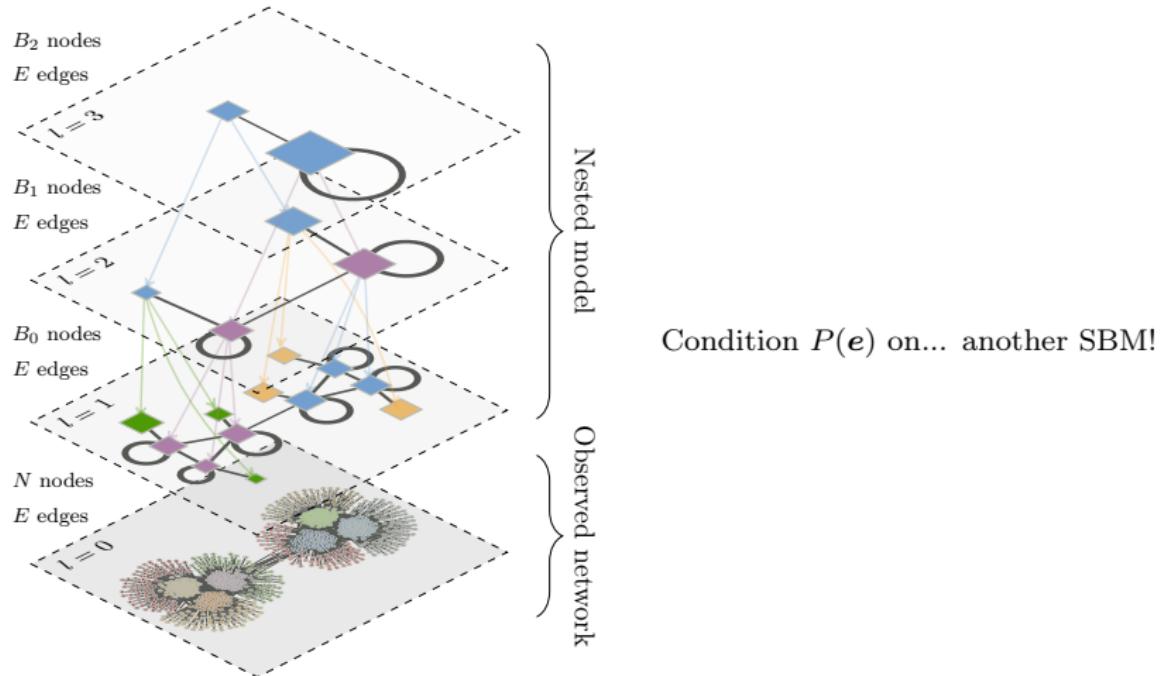


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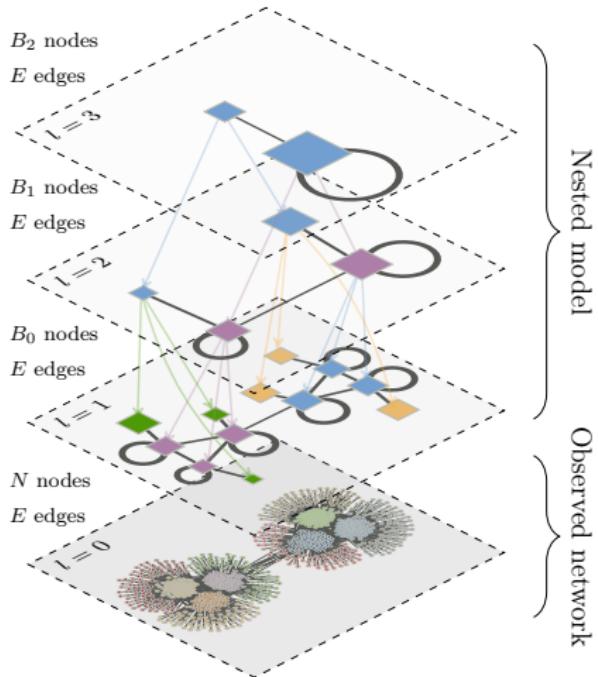
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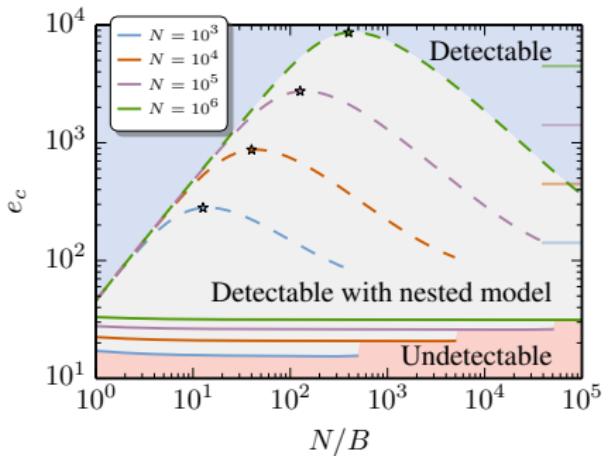
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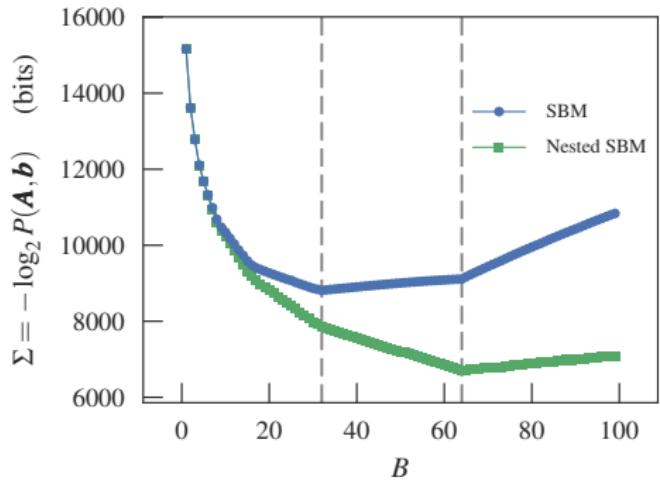


For planted partition:

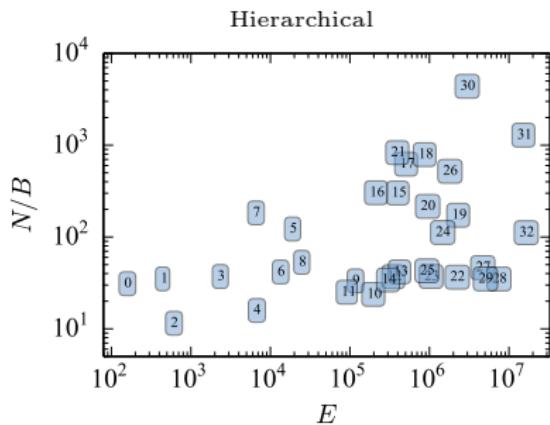
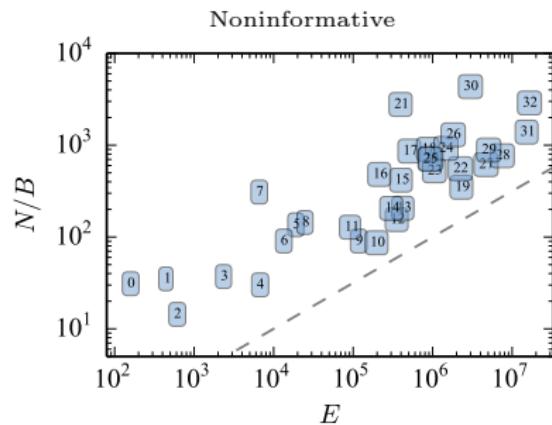
$$B_{\max} = O\left(\frac{N}{\log N}\right) \gg \sqrt{N}$$

# NESTED SBM PREVENTS UNDERFITTING

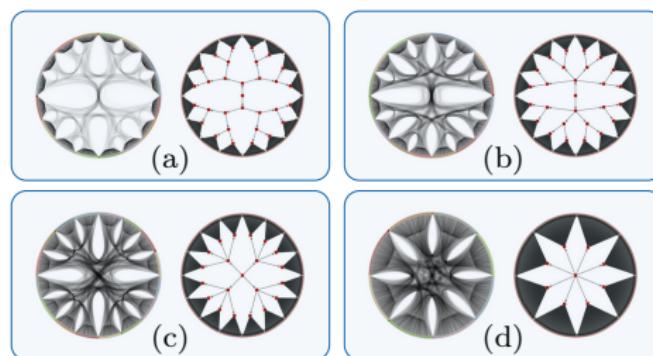
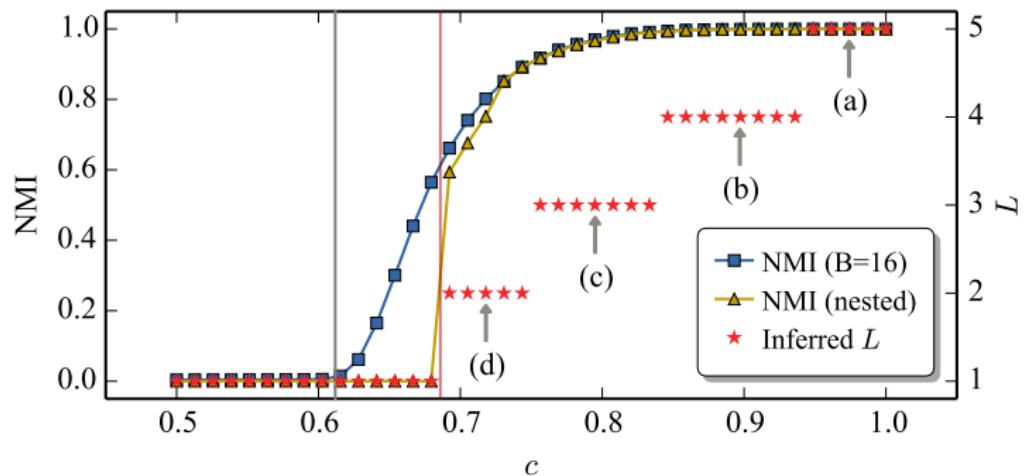
64 cliques of size 10



# RESOLUTION PROBLEM IN THE WILD

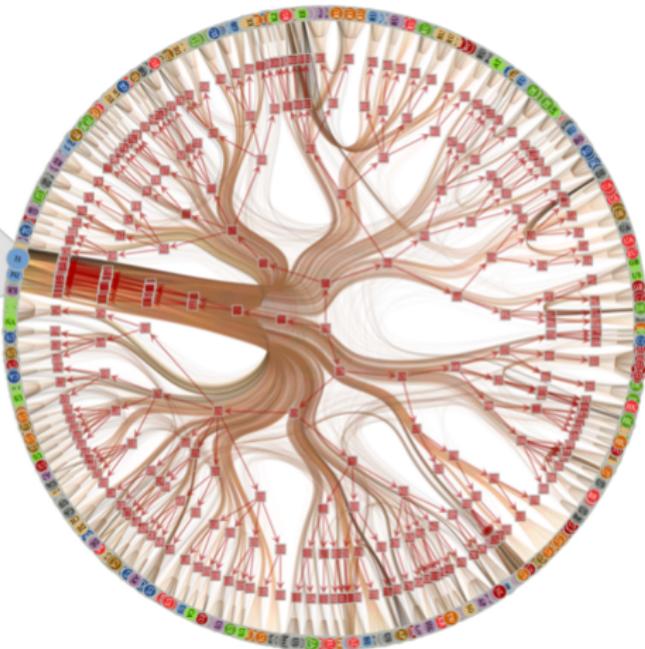
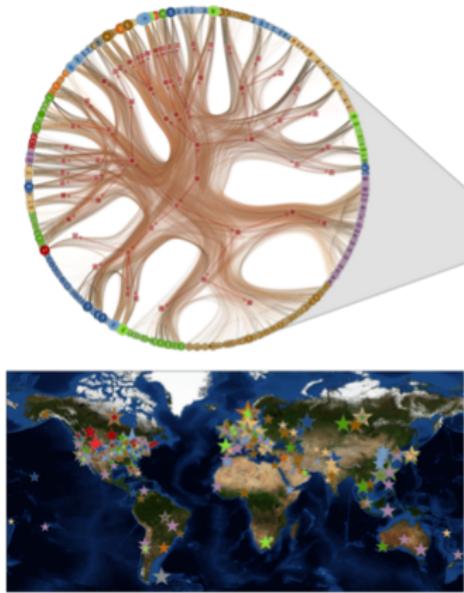


# HIERARCHICAL MODEL: BUILT-IN VALIDATION



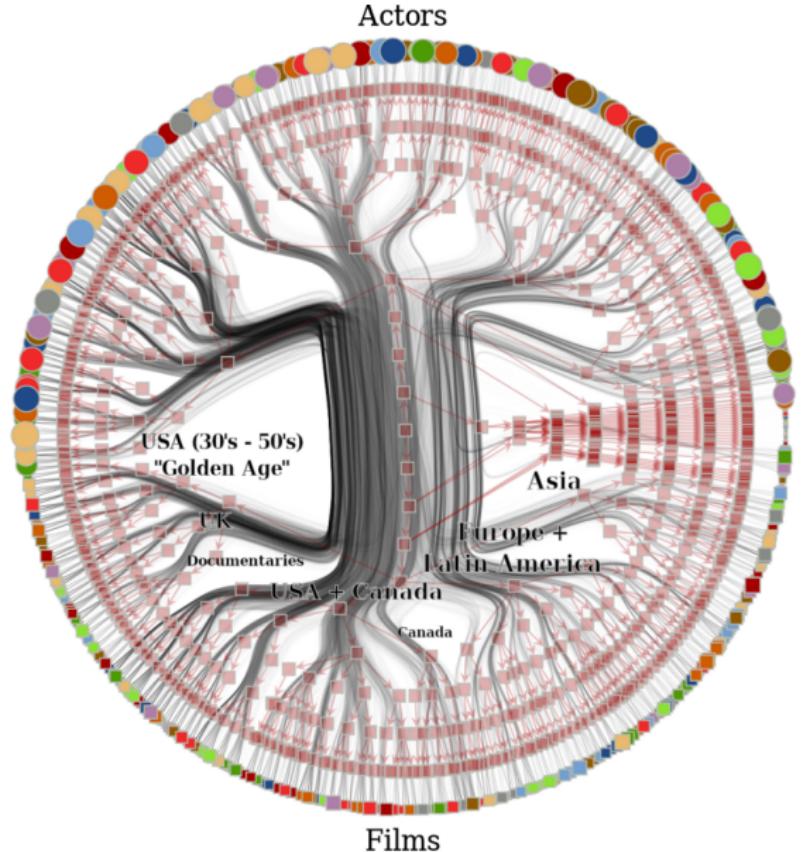
# NESTED SBM: MODELING AT MULTIPLE SCALES

Internet (AS)  
 $(N = 52,104, E = 399,625)$



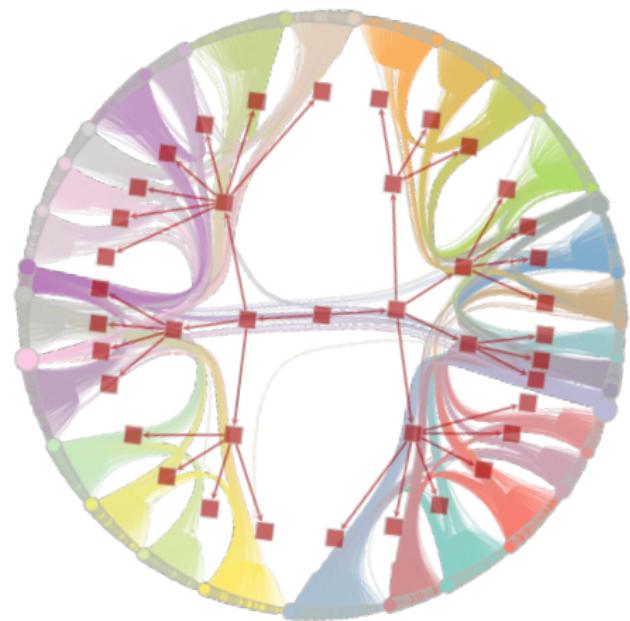
# NESTED SBM: MODELING AT MULTIPLE SCALES

IMDB FILM-ACTOR NETWORK ( $N = 372,447$ ,  $E = 1,812,312$ ,  $B = 717$ )



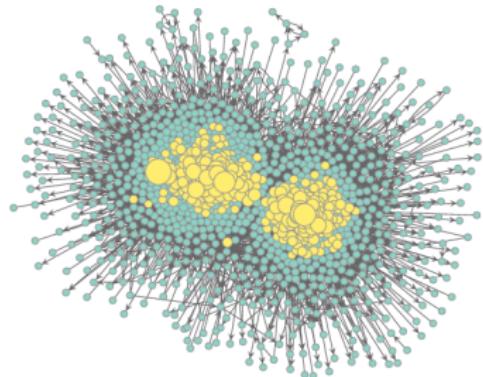
# NESTED SBM: MODELING AT MULTIPLE SCALES

## HUMAN CONNECTOME



# DEGREE-CORRECTION

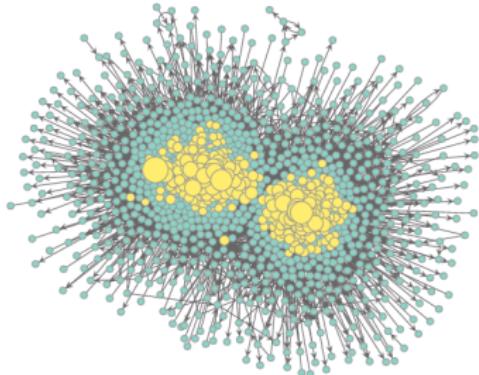
## Traditional SBM



# DEGREE-CORRECTION

Traditional SBM

Degree-corrected SBM



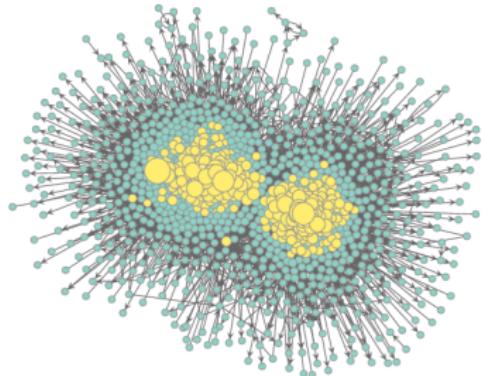
$$P(\mathbf{A}|\boldsymbol{\lambda}, \boldsymbol{\theta}, \mathbf{b}) = \prod_{i < j} \frac{(\theta_i \theta_j \lambda_{b_i b_j})^{A_{ij}} e^{-\theta_i \theta_j \lambda_{b_i b_j}}}{A_{ij}!} \times \prod_i \frac{(\theta_i^2 \lambda_{b_i b_i}/2)^{A_{ii}/2} e^{-\theta_i^2 \lambda_{b_i b_i}/2}}{(A_{ii}/2)!}$$

$\theta_i \rightarrow$  average degree of node  $i$

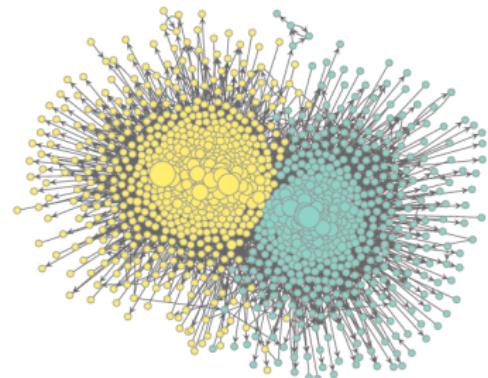
(Karrer and Newman 2011)

# DEGREE-CORRECTION

Traditional SBM



Degree-corrected SBM



$$P(\mathbf{A}|\boldsymbol{\lambda}, \boldsymbol{\theta}, \mathbf{b}) = \prod_{i < j} \frac{(\theta_i \theta_j \lambda_{b_i b_j})^{A_{ij}} e^{-\theta_i \theta_j \lambda_{b_i b_j}}}{A_{ij}!} \times \prod_i \frac{(\theta_i^2 \lambda_{b_i b_i}/2)^{A_{ii}/2} e^{-\theta_i^2 \lambda_{b_i b_i}/2}}{(A_{ii}/2)!}$$

$\theta_i \rightarrow$  average degree of node  $i$

(Karrer and Newman 2011)

# DEGREE-CORRECTED MICROCANONICAL SBM

Noninformative priors:

$$P(\boldsymbol{\lambda}|\boldsymbol{b}) = \prod_{r \leq s} e^{-\lambda_{rs}/(1+\delta_{rs})\bar{\lambda}} / (1 + \delta_{rs})\bar{\lambda}$$

$$P(\boldsymbol{\theta}|\boldsymbol{b}) = \prod_r (n_r - 1)! \delta(\sum_i \theta_i \delta_{b_i,r} - 1)$$

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Marginal likelihood:

$$\begin{aligned} P(\mathbf{A}|\mathbf{b}) &= \int P(\mathbf{A}|\boldsymbol{\lambda}, \boldsymbol{\theta}, \mathbf{b}) P(\boldsymbol{\lambda}|\mathbf{b}) P(\boldsymbol{\theta}|\mathbf{b}) d\boldsymbol{\lambda} d\boldsymbol{\theta} \\ &= \frac{\bar{\lambda}^E}{(\bar{\lambda} + 1)^{E+B(B+1)/2}} \times \frac{\prod_{r < s} e_{rs}! \prod_r e_{rr}!!}{\prod_{i < j} A_{ij}! \prod_i A_{ii}!!} \times \prod_r \frac{(n_r - 1)!}{(e_r + n_r - 1)!} \times \prod_i k_i! \end{aligned}$$

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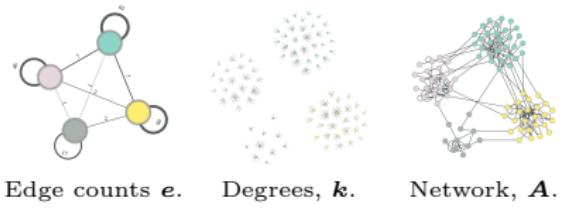
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Microcanonical equivalence:

$$P(\mathbf{A}|\mathbf{b}) = P(\mathbf{A}|\mathbf{k}, \mathbf{e}, \mathbf{b}) P(\mathbf{k}|\mathbf{e}, \mathbf{b}) P(\mathbf{e})$$

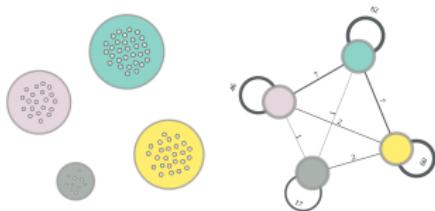
$$P(\mathbf{A}|\mathbf{k}, \mathbf{e}, \mathbf{b}) = \frac{\prod_{r < s} e_{rs}! \prod_r e_{rr}!! \prod_i k_i!}{\prod_{i < j} A_{ij}! \prod_i A_{ii}!! \prod_r e_r!!}$$

$$P(\mathbf{k}|\mathbf{e}, \mathbf{b}) = \prod_r \left( \binom{n_r}{e_r} \right)^{-1}$$

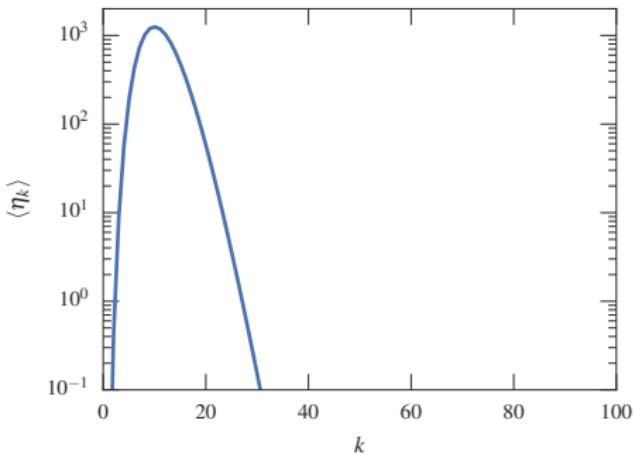


# PRIOR FOR THE DEGREES

Option 0: Random half-edges  
(Non-degree-corrected)



$$P(\mathbf{k}|\mathbf{e}, \mathbf{b}) = \prod_r \frac{e_r!}{n_r^{e_r} \prod_{i \in r} k_i!}$$



# PRIOR FOR THE DEGREES

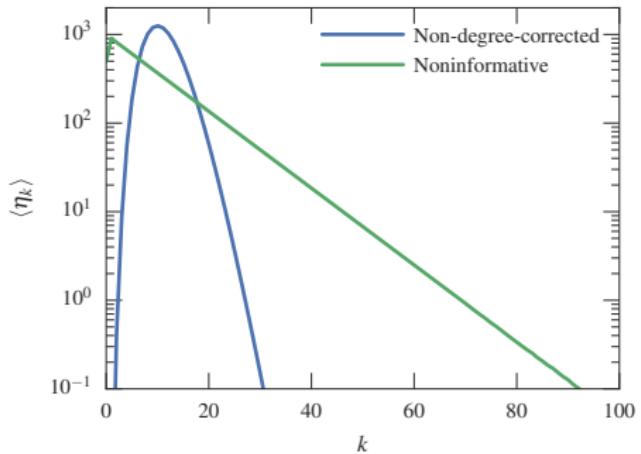
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## PRIOR FOR THE DEGREES

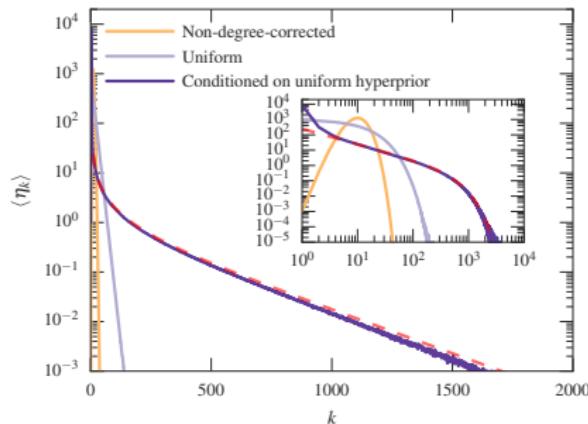
Option 2: Conditioned on degree distribution

$$\begin{aligned} P(\mathbf{k}|\mathbf{b}, \mathbf{e}) &= P(\mathbf{k}|\boldsymbol{\eta})P(\boldsymbol{\eta}) \\ &= \prod_r \frac{n_r!}{\prod_r \eta_k^r!} \times \prod_r q(e_r, n_r)^{-1} \end{aligned}$$

# PRIOR FOR THE DEGREES

Option 2: Conditioned on degree distribution

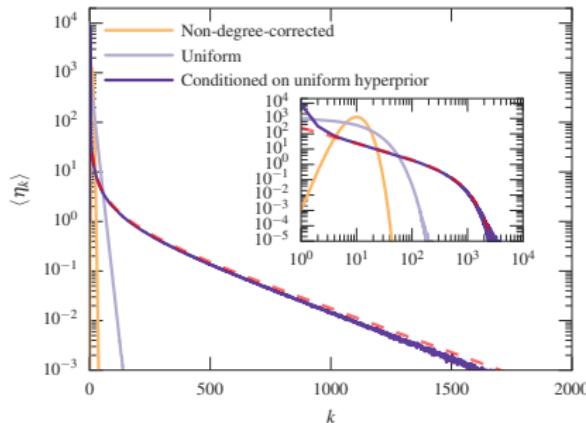
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## Bose-Einstein statistics

$N$  “bosons” (nodes)  
 $k_i \rightarrow$  “energy level” (degree)

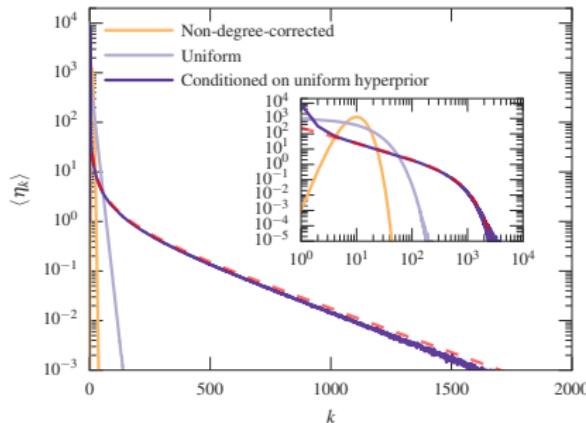
$$\langle \eta_k \rangle \approx \frac{1}{\exp(k\sqrt{\zeta(2)/E}) - 1}.$$

$$\langle \eta_k \rangle \approx \begin{cases} \sqrt{E/\zeta(2)}/k & \text{for } k \ll \sqrt{E}, \\ \exp(-k\sqrt{\zeta(2)/E}) & \text{for } k \gg \sqrt{E}. \end{cases}$$

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$$-\ln P(\mathbf{k}|\mathbf{e}, \mathbf{b}) \approx \sum_r n_r H(\boldsymbol{\eta}_r) + O(\sqrt{n_r})$$

$$H(\boldsymbol{\eta}_r) = - \sum_k (\eta_k^r/n_r) \ln(\eta_k^r/n_r)$$

## PRIOR FOR THE DEGREES: INTEGER PARTITIONS

$q(m, n) \rightarrow$  number of partitions of integer  $m$  into at most  $n$  parts

Exact computation

$$q(m, n) = q(m, n - 1) + q(m - n, n)$$

Full table for  $n \leq m \leq M$  in time  
 $O(M^2)$ .

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Approximation

$$q(m, n) \approx \frac{f(u)}{m} \exp(\sqrt{m}g(u)),$$

$$u = n/\sqrt{m}$$

$$f(u) = \frac{v(u)}{2^{3/2}\pi u} \left[ 1 - (1 + u^2/2)e^{-v(u)} \right]^{-1/2}$$

$$g(u) = \frac{2v(u)}{u} - u \ln(1 - e^{-v(u)})$$

$$v = u\sqrt{-v^2/2 - \text{Li}_2(1 - e^v)}$$

(Szekeres, 1951)

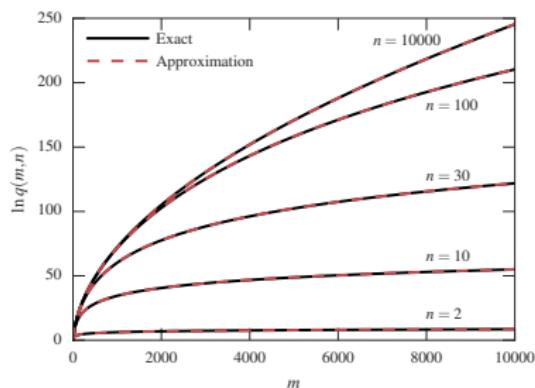
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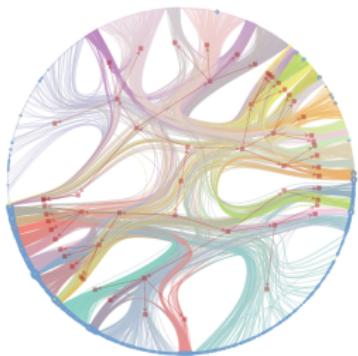
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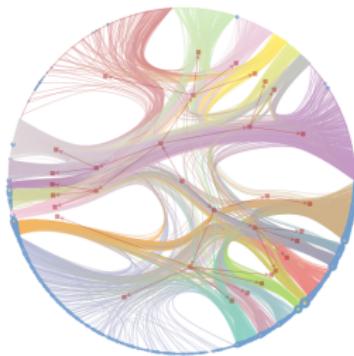
(Szekeres, 1951)

## EXAMPLE: POLITICAL BLOGS REDUX

$$N = 1,222, E = 19,027$$



(a) NDC-SBM,  $B_1 = 42$ ,  
 $\Sigma \approx 89938$  bits



(b) DC-SBM, uniform  
prior,  $B_1 = 23$ ,  $\Sigma \approx 87162$   
bits



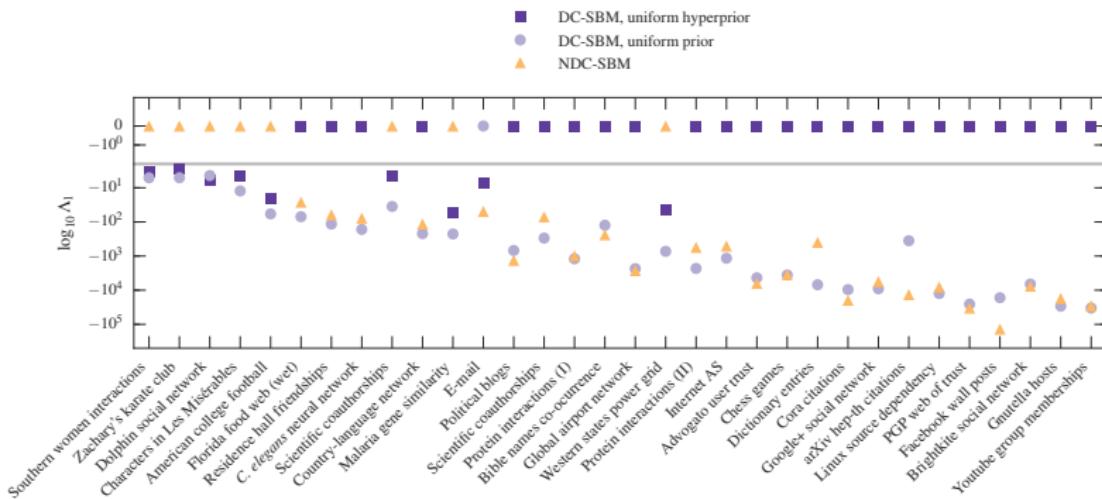
(c) DC-SBM, uniform  
hyperprior,  $B_1 = 20$ ,  
 $\Sigma \approx 84890$  bits

# MODEL SELECTION

$$\Lambda = \frac{P(\mathbf{A}, \{\mathbf{b}_l\} | \mathcal{C}_1) P(\mathcal{C}_1)}{P(\mathbf{A}, \{\mathbf{b}'_l\} | \mathcal{C}_2) P(\mathcal{C}_2)} = 2^{-\Delta\Sigma}$$

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## INFERRING GROUP ASSIGNMENTS: SAMPLING VS. MAXIMIZATION

$\hat{\mathbf{b}} \rightarrow$  estimator,  $\mathbf{b}^* \rightarrow$  true partition

Maximum *a posteriori* (MAP)

Indicator loss function:

$$\Delta(\hat{\mathbf{b}}, \mathbf{b}^*) = \prod_i \delta_{\hat{b}_i, b_i^*}$$

Maximization over the posterior

$$\sum_{\mathbf{b}} \Delta(\hat{\mathbf{b}}, \mathbf{b}) P(\mathbf{b} | \mathbf{A})$$

yields the MAP estimator

$$\hat{\mathbf{b}} = \operatorname{argmax}_{\mathbf{b}} P(\mathbf{b} | \mathbf{A}).$$

(Identical to MDL.)

Node marginals

Overlap loss function:

$$d(\hat{\mathbf{b}}, \mathbf{b}^*) = \frac{1}{N} \sum_i \delta_{\hat{b}_i, b_i^*}$$

Maximization over the posterior

$$\sum_{\mathbf{b}} d(\hat{\mathbf{b}}, \mathbf{b}) P(\mathbf{b} | \mathbf{A})$$

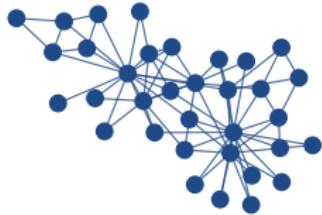
yields the marginal estimator

$$\hat{b}_i = \operatorname{argmax}_r \pi_i(r),$$

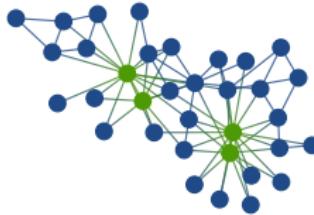
$$\pi_i(r) = \sum_{\mathbf{b} \setminus b_i} P(b_i = r, \mathbf{b} \setminus b_i | \mathbf{A}).$$

# SAMPLING VS. MAXIMIZATION

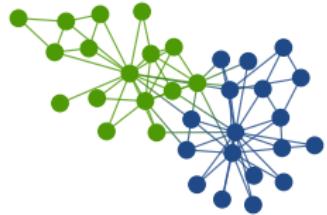
Zachary's karate club



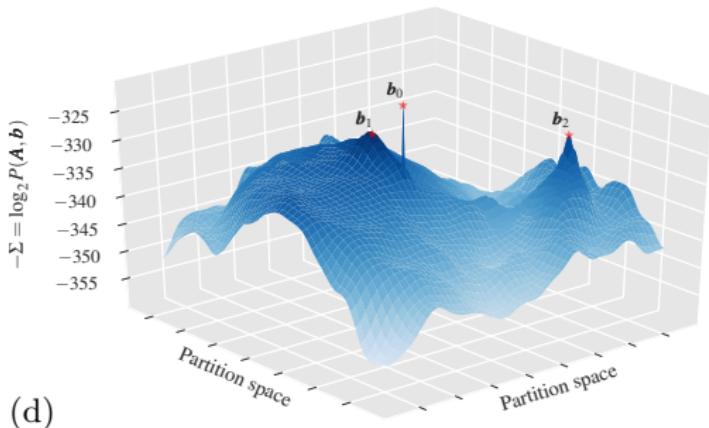
(a)  $\mathbf{b}_0$ ,  $\Sigma = 321.3$  bits



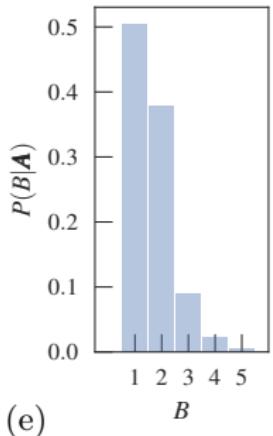
(b)  $\mathbf{b}_1$ ,  $\Sigma = 327.5$  bits



(c)  $\mathbf{b}_2$ ,  $\Sigma = 329.3$  bits



(d)



(e)

# SAMPLING VS. MAXIMIZATION

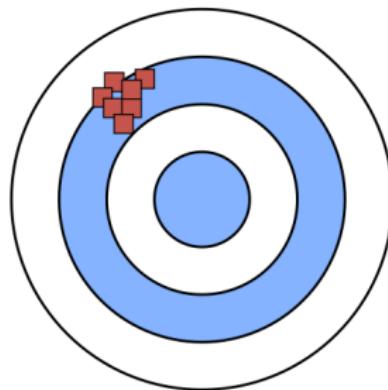
## BIAS-VARIANCE TRADE-OFF

### Maximization (MDL)

$$\{\hat{\mathbf{b}}_l\} = \operatorname{argmax}_{\{\mathbf{b}_l\}} P(\{\mathbf{b}_l\}|\mathbf{A})$$

Finds the best partition, and number of groups  $\{B_l\}$ .

*Lower variance, higher bias*



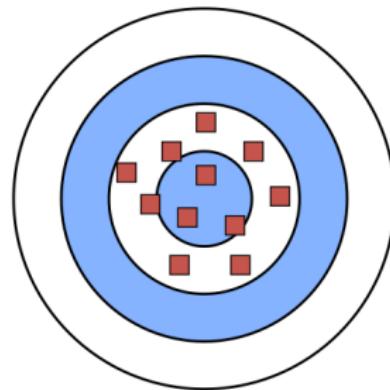
*Tendency to **underfit**.*

### Sampling

$$\{\mathbf{b}_l\} \sim P(\{\mathbf{b}_l\}|\mathbf{A})$$

Finds the best posterior ensemble; marginal posterior  $P(B_l|\mathbf{A})$ .

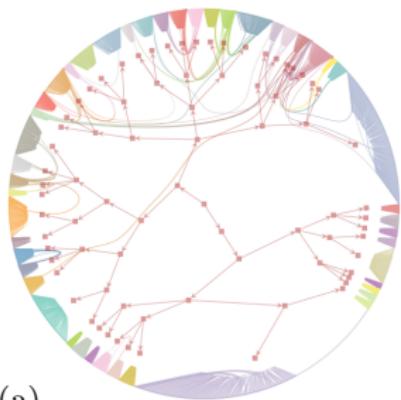
*Higher variance, lower bias*



*Tendency to **overfit**.*

# SAMPLING VS. MAXIMIZATION

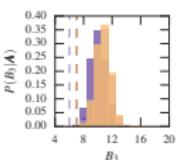
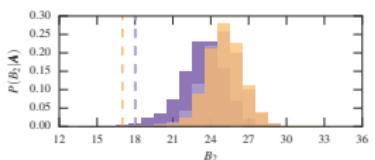
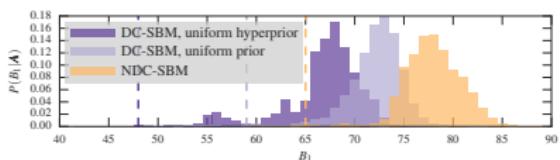
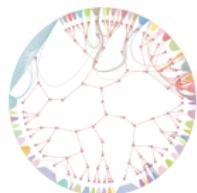
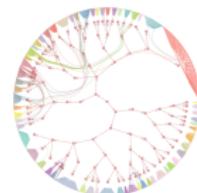
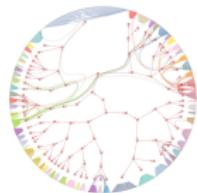
Collaborations between scientists ( $N = 1,589$ ,  $E = 2,742$ )



(a)



(b)



# INFERENCE ALGORITHM: METROPOLIS-HASTINGS

- ▶ Move proposal,  $b_i = r \rightarrow b_i = s$
- ▶ Accept with probability

$$a = \min \left( 1, \frac{P(\mathbf{b}'|\mathbf{A})P(\mathbf{b} \rightarrow \mathbf{b}')}{P(\mathbf{b}|\mathbf{A})P(\mathbf{b}' \rightarrow \mathbf{b})} \right).$$

Move proposal of node  $i$  requires  $O(k_i)$  operations. A whole MCMC sweep can be performed in  $O(E)$  time, **independent of the number of groups,  $B$ .**

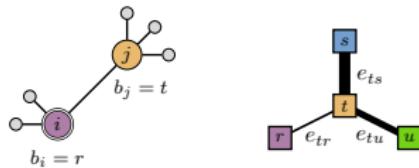
In contrast to:

1. EM + BP with Bernoulli SBM:  $O(EB^2)$  (Semiparametric) [Decelle et al, 2011]
2. Variational Bayes with (overlapping) Bernoulli SBM:  $O(EB)$  (Semiparametric) [Gopalan and Blei, 2011]
3. Bernoulli SBM with noninformative priors:  $O(EB^2)$  (Greedy) [Côme and Latouche, 2015]
4. Poisson SBM with noninformative priors:  $O(EB^2)$  (heat bath) [Newman and Reinert, 2016]

# EFFICIENT INFERENCE: OTHER IMPROVEMENTS

## Smart move proposals

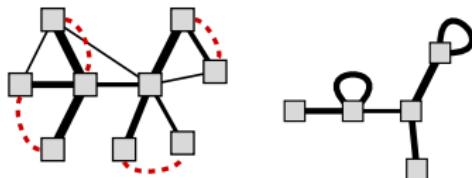
- ▶ Choose a random vertex  $i$  (happens to belong to group  $r$ ).
- ▶ Move it to a random group  $s \in [1, B]$ , chosen with a probability  $p(r \rightarrow s|t)$  proportional to  $e_{ts} + \epsilon$ , where  $t$  is the group membership of a randomly chosen neighbour of  $i$ .



Fast mixing times.

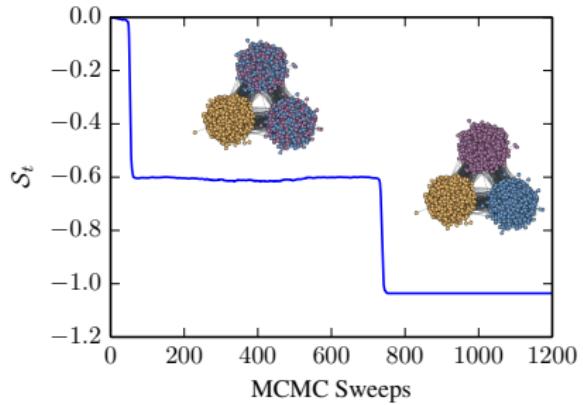
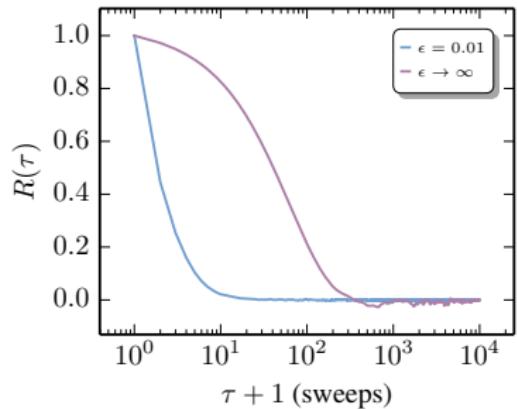
## Agglomerative initialization

- ▶ Start with  $B = N$ .
- ▶ Progressively merge groups.



Avoids metastable states.

## EFFICIENT INFERENCE: OTHER IMPROVEMENTS



Greedy heuristic:  $P(\mathbf{b}|\mathbf{A})^\beta$ ,  $\beta \rightarrow \infty$

