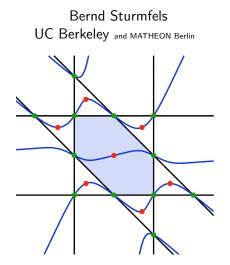
The Central Curve in Linear Programming



joint work with Jesus De Loera and Cynthia Vinzant

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Linear Programming

primal: Maximize $\mathbf{c}^T \mathbf{x}$ subject to $A\mathbf{x} = \mathbf{b}$ and $\mathbf{x} \ge 0$

dual: Minimize $\mathbf{b}^T \mathbf{y}$ subject to $A^T \mathbf{y} - \mathbf{s} = \mathbf{c}$ and $\mathbf{s} \ge 0$

A is a fixed matrix of rank d having n columns,. The vectors $\mathbf{c} \in \mathbb{R}^n$ and $\mathbf{b} \in \text{image}(A)$ may vary.

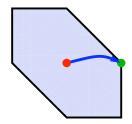
For any $\lambda > 0$, the *logarithmic barrier function* for the primal is

$$f_{\lambda}(\mathbf{x}) := \mathbf{c}^{T}\mathbf{x} + \lambda \sum_{i=1}^{n} \log x_{i},$$

This function is concave. Let $\mathbf{x}^*(\lambda)$ be the unique solution of

barrier : Maximize $f_{\lambda}(\mathbf{x})$ subject to $A\mathbf{x} = \mathbf{b}$ and $\mathbf{x} \ge 0$

The Central Path



The set of all (primal) feasible solutions is a convex polytope

$$P \quad = \quad \big\{ \mathbf{x} \in \mathbb{R}^n_{\geq 0} : A\mathbf{x} = \mathbf{b} \big\}.$$

The logarithmic barrier function $f_{\lambda}(\mathbf{x})$ is defined on the relative interior of P. It tends to $-\infty$ when \mathbf{x} approaches the boundary.

The *primal central path* is the curve $\{\mathbf{x}^*(\lambda) \mid \lambda > 0\}$ inside *P*. It connects the *analytic center* of *P* with the optimal solution:

$$\mathbf{x}^*(\infty) \longrightarrow \cdots \longrightarrow \mathbf{x}^*(\lambda) \longrightarrow \cdots \longrightarrow \mathbf{x}^*(0).$$

Complementary Slackness

Optimal primal and dual solutions are characterized by

$$\begin{aligned} A\mathbf{x} &= \mathbf{b} , \ A^T \mathbf{y} - \mathbf{s} = \mathbf{c} , \ \mathbf{x} \ge 0 , \ \mathbf{s} \ge 0, \\ \text{and} \quad x_i \cdot s_i \ = \ 0 \ \text{for} \ i = 1, 2, \dots, n. \end{aligned}$$
(1)

In textbooks on Linear Programming we find

Theorem

For all $\lambda > 0$, the system of polynomial equations

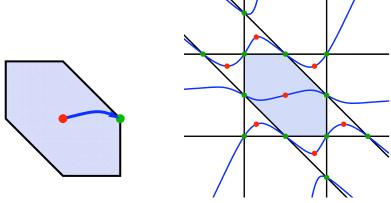
$$A\mathbf{x} = \mathbf{b}, \ A^T \mathbf{y} - \mathbf{s} = \mathbf{c}, \ and \ x_i s_i = \lambda \ for \ i = 1, 2, \dots, n,$$

has a unique real solution $(\mathbf{x}^*(\lambda), \mathbf{y}^*(\lambda), \mathbf{s}^*(\lambda))$ with $\mathbf{x}^*(\lambda) > 0$ and $\mathbf{s}^*(\lambda) > 0$. The point $\mathbf{x}^*(\lambda)$ solves the barrier problem.

The limit point $(\mathbf{x}^*(0), \mathbf{y}^*(0), \mathbf{s}^*(0))$ uniquely solves (1).

Our Contributions

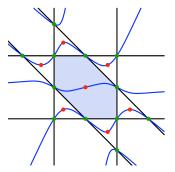
Bayer-Lagarias (1989) showed that the central path is an algebraic curve, and they suggested the problem of identifying its prime ideal. We resolve this problem.



The central curve is the Zariski closure of the central path.

Our Contributions

The central curve is the union of the central paths over all polyhedra in the hyperplane arrangement:



Dedieu-Malajovich-Shub (2005) studied the global curvature of the central path, by bounding the degree of corresponding Gauss curve. We offer a refined bound.

Curvature is important for numerical interior point methods. Deza-Terlaky-Zinchenko (2008): continuous Hirsch conjecture. Central Curves in the Plane The dual problem for d = 2 is

Minimize $\mathbf{b}^{\mathsf{T}}\mathbf{y}$ subject to $A^{\mathsf{T}}\mathbf{y} \ge \mathbf{c}$

The central curve has the parametric representation

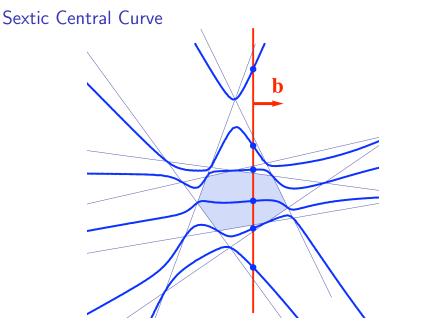
$$\mathbf{y}^{*}(\lambda) = \operatorname{argmin}_{\mathbf{y} \in \mathbb{R}^{2}} \frac{b_{1}y_{1} + b_{2}y_{2}}{b_{1}y_{1} + b_{2}y_{2}} - \lambda \sum_{i=1}^{n} \log(a_{1i}y_{1} + a_{2i}y_{2} - c_{i}).$$

Its defining polynomial is

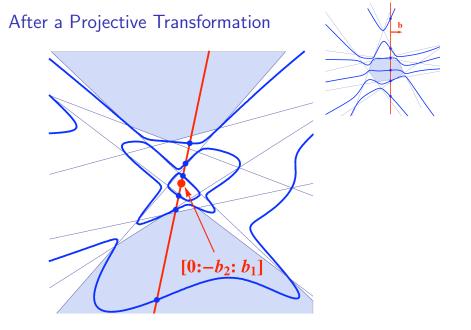
$$\mathcal{C}(y_1, y_2) = \sum_{i \in \mathcal{I}} (b_1 a_{2i} - b_2 a_{1i}) \prod_{j \in \mathcal{I} \setminus \{i\}} (a_{1j} y_1 + a_{2j} y_2 - c_j),$$

where $\mathcal{I} = \{i : b_1 a_{2i} - b_2 a_{1i} \neq 0\}$. The degree equals $|\mathcal{I}| - 1$. Proposition

The central curve C is hyperbolic with respect to the point $[0: -b_2: b_1]$. This means that every line in $\mathbb{P}^2(\mathbb{R})$ passing through this special point meets C only in real points.



.... obtained as the *polar curve* of an arrangement of n = 7 lines.



hyperbolic curve = Vinnikov curve \rightarrow Spectrahedron

Inflection Points

The number of inflection points of a plane curve of degree D in $\mathbb{P}^2_{\mathbb{C}}$ is at most 3D(D-2).

Felix Klein (1876) proved: The number of real inflection points of a plane curve of degree D is at most D(D-2).

Theorem: The average total curvature of a central curve in the plane is at most 2π .

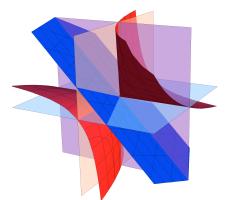
Dedieu (2005) et. al. had the bound 4π .

Question: What is the largest number of inflection points on a single oval of a hyperbolic curve of degree D in the real plane? In particular, is this number *linear* in the degree D?

Central Sheet

Back to the primal problem in arbitrary dimensions...

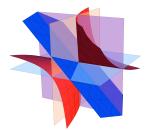
Let $K = \mathbb{Q}(A)(\mathbf{b}, \mathbf{c})$ and $\mathcal{L}_{A,\mathbf{c}}$ the subspace of K^n spanned by the rows of A and the vector \mathbf{c} .



Define the *central sheet* to be its coordinatewise reciprocal. Denoted \mathcal{L}_{Ac}^{-1} , this is the Zariski closure of the set

$$\left\{ \left(\frac{1}{u_1}, \dots, \frac{1}{u_n}\right) \in \mathbb{C}^n : (u_1, \dots, u_n) \in \mathcal{L}_{A, \mathbf{c}} \text{ and } u_i \neq 0 \text{ for all } i \right\}$$

Equations



Lemma

The primal central curve C equals the intersection of the central sheet $\mathcal{L}_{A,c}^{-1}$ with the affine space $\{A \cdot \mathbf{x} = \mathbf{b}\}$.

Theorem

The prime ideal of polynomials that vanish on the central curve C is $\langle A\mathbf{x} - \mathbf{b} \rangle + J_{A,\mathbf{c}}$, where $J_{A,\mathbf{c}}$ is the ideal of the central sheet $\mathcal{L}_{A,\mathbf{c}}^{-1}$. The common degree of C and $\mathcal{L}_{A,\mathbf{c}}^{-1}$ is the Möbius number $|\mu(A,\mathbf{c})|$.

Proudfoot and Speyer (2006) found a universal Gröbner basis for the prime ideal $J_{A,c}$ of the central sheet $\mathcal{L}_{A,c}^{-1}$.

We use this to answer the question of Bayer and Lagarias (1989).

Details

The universal Gröbner basis of $J_{A,c}$ consists of the polynomials

$$\sum_{i\in \mathrm{supp}(v)} v_i \cdot \prod_{j\in \mathrm{supp}(v)\setminus\{i\}} x_j,$$

where (v_1, \ldots, v_n) runs over the cocircuits of the linear space $\mathcal{L}_{A,c}$.

Cocircuits means non-zero vectors of minimal support.

The Möbius number $|\mu(A, \mathbf{c})|$ is an invariant from matroid theory. It gives the degree of the central curve. If A and **c** are generic then

$$|\mu(A,\mathbf{c})| = \binom{n-1}{d}.$$

Proudfoot and Speyer (2006) also determine the Hilbert series

Example: 2×3 Transportation Problem

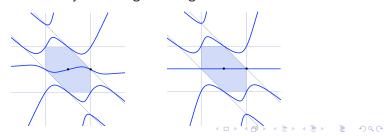
Let d = 4, n = 6 and A the linear map taking a matrix $\binom{x_1 x_2 x_3}{x_4 x_5 x_6}$ to its row and column sums. The ideal of the affine subspace is

$$I_{A,\mathbf{b}} = \langle x_1 + x_2 + x_3 - b_1, x_4 + x_5 + x_6 - b_2, x_1 + x_4 - b_3, x_2 + x_5 - b_4 \rangle.$$

The central sheet $\mathcal{L}_{A,\mathbf{c}}^{-1}$ is the quintic hypersurface

$$f_{A,\mathbf{c}}(\mathbf{x}) = \det \begin{pmatrix} 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ c_1 & c_2^{-1} & c_3^{-1} & c_4^{-1} & c_5^{-1} & c_6^{-1} \\ x_1^{-1} & x_2^{-1} & x_3^{-1} & x_4^{-1} & x_5^{-1} & x_6^{-1} \end{pmatrix} \cdot x_1 x_2 x_3 x_4 x_5 x_6.$$

The central curve is defined by $I_{A,\mathbf{b}} + \langle f_{A,\mathbf{c}} \rangle$. It is irreducible for any **b** as long as **c** is generic:



Applying the Gauss Map

Dedieu-Malajovich-Shub (2005): The total curvature of any real algebraic curve \mathcal{C} in \mathbb{R}^m is the arc length of its image under the Gauss map $\gamma : \mathcal{C} \to \mathbb{S}^{m-1}$. This quantity is bounded above by π times the degree of the projective Gauss curve in \mathbb{P}^{m-1} . In symbols,

$$\int_{\mathsf{a}}^{b} ||rac{d\gamma(t)}{dt}|| dt \ \leq \ \pi \cdot \deg(\gamma(\mathcal{C})).$$

Our Theorem: The degree of the projective Gauss curve of the central curve C satisfies a bound in terms of matroid invariants:

$$\deg(\gamma(\mathcal{C})) \leq 2 \cdot \sum_{i=1}^{d} i \cdot \mathbf{h}_{i} \leq 2 \cdot (n-d-1) \cdot \binom{n-1}{d-1}.$$

 $(h_0, h_1, \ldots, h_d) =$ h-vector of the broken circuit complex of $\mathcal{L}_{A,c}$

Example

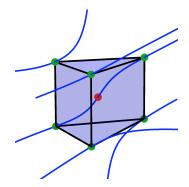
$$n = 5, \ d = 2.$$

$$A = \begin{pmatrix} 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 \end{pmatrix} \qquad \mathbf{b} = \begin{pmatrix} 3 \\ 2 \end{pmatrix} \qquad \mathbf{c} = \begin{pmatrix} 1 & 2 & 0 & 4 & 0 \end{pmatrix}$$

Equations for C:

$$2x_2x_3 - x_1x_3 - x_1x_2,
4x_2x_4x_5 - 4x_1x_4x_5 + x_1x_2x_5 - x_1x_2x_4,
4x_3x_4x_5 - 4x_1x_4x_5 - x_1x_3x_5 + x_1x_3x_4,
4x_3x_4x_5 - 4x_2x_4x_5 - 2x_2x_3x_5 + 2x_2x_3x_4,$$

 $x_1 + x_2 + x_3 = 3$, $x_4 + x_5 = 2$



 $h = (1,2,2) \Rightarrow deg(\mathcal{C}) = 5 \text{ and } deg(\gamma(\mathcal{C})) \leq 12$

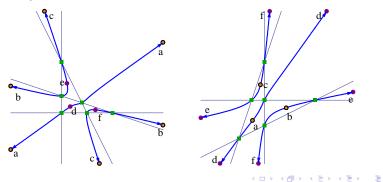
Primal-Dual Curve

Let \mathcal{L} denote the row space of the matrix A and \mathcal{L}^{\perp} its orthogonal complement in \mathbb{R}^n . Fix a vector $\mathbf{g} \in \mathbb{R}^n$ such that $A\mathbf{g} = \mathbf{b}$.

The primal-dual central path $(\mathbf{x}^*(\lambda), \mathbf{s}^*(\lambda))$ has the following description that is symmetric under duality:

$$\mathbf{x} \in \mathcal{L}^{\perp} + \mathbf{g}$$
, $\mathbf{s} \in \mathcal{L} + \mathbf{c}$ and $x_1 s_1 = x_2 s_2 = \cdots = x_n s_n = \lambda$.

These equations define an irreducible curve in $\mathbb{P}^n \times \mathbb{P}^n$.



Analytic Centers

Consider the dual pair of hyperplane arrangements

$$\mathcal{H} = \{x_i = 0\}_{i \in [n]}$$
 in $\mathcal{L}^{\perp} + \mathbf{g} \subset \mathbb{P}^n \setminus \{x_0 = 0\}$

 $\mathcal{H}^* = \{s_i = 0\}_{i \in [n]} \text{ in } \mathcal{L} + \mathbf{c} \subset \mathbb{P}^n \setminus \{s_0 = 0\}$

Proposition

The intersection $\mathcal{L}^{-1} \cap (\mathcal{L}^{\perp} + \mathbf{g})$ is a zero-dimensional variety. All its points are defined over \mathbb{R} . They are the analytic centers of the polytopes that form the bounded regions of the arrangement \mathcal{H} .

Proposition

The intersection $(\mathcal{L}^{\perp})^{-1} \cap (\mathcal{L} + \mathbf{c})$ is a zero-dimensional variety. All points are defined over \mathbb{R} . They are the analytic centers of the polytopes that form the bounded regions of the arrangement \mathcal{H}^* .

Global Geometry

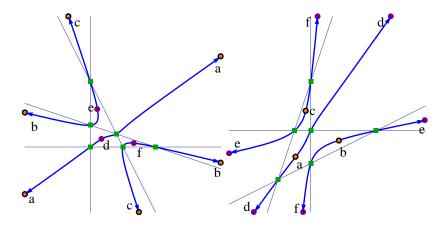
Theorem

The primal central curve in **x**-space \mathbb{R}^n passes through all vertices of \mathcal{H} . In between these vertices, it passes through the analytic centers of the bounded regions. Similarly, the dual central curve in **s**-space passes through all vertices and analytic centers of \mathcal{H}^* .

Along the curve, vertices of \mathcal{H} correspond to vertices of \mathcal{H}^* .

The analytic centers of bounded regions of \mathcal{H} correspond to points on the dual curve in s-space at the hyperplane $\{s_0 = 0\}$, and the analytic centers of bounded regions of \mathcal{H}^* correspond to points on the primal curve in x-space at the hyperplane $\{x_0 = 0\}$.

A Curve in $\mathbb{P}^2\times\mathbb{P}^2$



Conclusion

... for Pure Mathematicians: Optimization is Beautiful.

... for Applied Mathematicians: Algebraic Geometry is Useful.

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Is there a difference between "Pure" and "Applied" ?