## Determining the Effects of Social Network Evolution

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# AIMS SA Muizenberg





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Cosmology and Astrophysics, Mathematical and Physical Biosciences, Mathematical Finance and Mathematical Foundation and Scientific Computing.

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# 2016/17 Structured Masters Students





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A group is defined as "a finite set of actors who for conceptual theoretical, or empirical reasons are treated as a finite set of individuals on which network measurements are made" (Wasserman and Faust, 1994).

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## 2016/17 Structured MSc Social Network



Figure: AIMS Network, December,  $\mathbf{x}(t_0)$  (left) and April,  $\mathbf{x}(t_1)$  (right) The size of each node is proportional to in-degree. The shape of the node represents the actors sex, and the colour of nodes represent counter

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What are the **mechanisms** that determine social network evolution from  $t_0$  to  $t_1$ ?





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Coleman, 1964

Continuous-time evolution although discrete time observations.



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Modelled evolution as continuous-time Markov process.



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Snijders, 2001

Continuous-time Markov Process with multiple effects.

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#### Continuous-Time Markov Process [Taylor and Karlin, 1998]

- $\mathcal{X} = \{\mathbf{x}(t) | t \in T\}$  is state space of all stochastic processes of order  $2^{n(n-1)}$ .
- $T = \{t \in \mathbb{R}^+ | t_0 \le t \le t_1\}.$
- $P_{ij}(t,s) = P[\mathbf{x}(t+s) = j | \mathbf{x}(t) = i].$
- $P_{ij}(t,s) = \prod_{k,l} P\{\mathbf{x}_{kl}(t+s) = j_{kl} | \mathbf{x}(t) = i\} + o(s).$
- $P_{ij}(t,s) = P[\mathbf{x}(s) = j | \mathbf{x}(0) = i] = P_{ij}(s).$
- Regularity.
- Infinitesimal Generator,  $q_{ij}$ , rate of change of transition.

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• Markov process: initialise  $\mathbf{x}(0) = i$ . Soujourn in state *i* for a time exponentially distributed with parameter  $q_{ii}$ . Transition to state *j* with probability  $p_{ij} = \frac{q_{ij}}{q_{ii}}$  and repeat.

## Stochastic Actor-Oriented Model [Snijders, 2001]

- Continuous-time.
- Markovian network.
- Discrete choice model,  $\mathbf{x}(i \rightsquigarrow j)$ .



## Choices/Mechanisms/Effects

Assume the choice to make or break a tie with n-1 other actors in the network is individuals own choice and dependent on network and covariate effects.

Effect	Network Statistic	Effective Tran	sitions in Network <sup>a</sup>	Verbal Description
1. Outdegree	$\sum_{j} \mathbf{x}_{ij}$	${\scriptstyle } {\scriptstyle \end{array}}$	<b></b>	Overall tendency to have ties
2. Reciprocity	$\sum_{j} \mathbf{x}_{ij} \mathbf{x}_{ji}$	$   \leftrightarrow  \leftrightarrow $	00	Tendency to have reciprocated ties
3. Preferential attachment	$\sum_{j} x_{ij} \sqrt{\sum_{h} x_{hj}}$	●		Tendency to attach to popular others (with decreasing marginal sensitivity to alter's popularity)
4. Transitive triplets	$\sum_{j} x_{ij} \sum_{h} x_{ih} x_{hj}$	$\overset{}{\overset{}}_{\overset{}{}} \leftrightarrow$		Tendency toward triadic closure of the neighborhood (linear effect of the number of indirect ties)
5. Transitive ties	$\sum_j x_{ij} \max_h(x_{ih}x_{hj})$	(number of interm)	mediaries is irrelevant)	Tendency toward triadic closure of the neighborhood (binary effect of indirect ties)
6. Actors at distance 2	$\sum_{j}{(1-x_{ij})} \max_{h}(x_{ih}x_{hj})$	(number of interm)	⊕→→→⊕ nediaries is irrelevant)	Tendency to keep others at social distance 2 (negative measure of triadic closure)

TABLE 2 Selection of Possible Effects for Modeling Network Evolution

Figure: Dynamic Networks and Behaviour: Separating Selection From Influence, Steglich et al., 2010.

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## **Discrete Choice Model**

**Rate Function**: rate at which actor *i* chooses to select or deselect friendship. Assume constant:  $\lambda$ .

**Objective Function**: Perceived utility, of actor *i*, for chosen network configuration,  $\mathbf{x}(i \rightsquigarrow j)$ ,

$$f(i, \mathbf{x}(i \rightsquigarrow j)) = \sum_{s=1}^{L} \beta_{s} \rho_{s}(i, \mathbf{x}(i \rightsquigarrow j)).$$



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Discrete Choice Model [Maddala, 1983]:

$$max_{j\in V(\mathbf{x})}(f(i,\mathbf{x}(i\rightsquigarrow j))+U_j),$$

where  $U_j$  (assumed i.i.d Gumbel). Probability multinomial logistic regression given by

$$p_{ij}(\mathbf{x}(i \rightsquigarrow j)) = \frac{\exp(f(i, \mathbf{x}(i \rightsquigarrow j)) - f(i, \mathbf{x}))}{\sum_{h=1, h \neq i}^{n} \exp(f(i, \mathbf{x}(i \rightsquigarrow h)) - f(i, \mathbf{x}))} \cdot \frac{\exp(f(i, \mathbf{x}(i \rightsquigarrow h)) - f(i, \mathbf{x}))}{\operatorname{AIMS}} \cdot \frac{\operatorname{AIMS}}{\operatorname{AIMS}}$$

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#### Markov Process

A Markov process is completely defined by the space of all possible states  $\mathcal{X}$ , the initial state,  $\mathbf{x}(t_0)$ , and the transition rate matrix Q,

$$q_{ij} = \lambda p_{ij}.$$

Model is dependent on unknown parameters  $\hat{\theta} = (\hat{\lambda}, \hat{\beta})$ .

- Initialise:  $t = 0, \mathbf{x}(t_0), \rho$  and  $\hat{\theta}$ .
- **2** Sample *i* from uniform distribution.
- **3** Given actor *i*, sample *j* with probability  $p_{ij}(\mathbf{x}(i \rightsquigarrow j))$ .
- Let  $t = t + \Delta t$  for  $\Delta t$  sampled exponential random variable with parameter  $n\hat{\lambda}$ .
- **(a)** Change network  $\mathbf{x}(t)(i \rightsquigarrow j)$ .
- Repeat step (b) until  $t = T_1$ .

Denote the final output  $\mathbf{x}(T_1)$ .  $\mathbf{x}$  is therefore dependent on  $T_1$  $\mathbf{x}(t_0)$ ,  $\boldsymbol{\rho}$  and  $\hat{\boldsymbol{\theta}}$ .

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## Parameter Estimation

Method of Moments [Snijders, 2001]:

$$E[Z(\boldsymbol{x}(T_1, \hat{\boldsymbol{\theta}})) | \boldsymbol{x}(t_0), \boldsymbol{\rho}] = z^{obs},$$
  
for  $\hat{\boldsymbol{\theta}} = (\hat{\lambda}, \hat{\boldsymbol{\beta}})$ . Chose  $Z = (C(t), \boldsymbol{P}(t))$  where  
 $C = ||\boldsymbol{x}(t) - \boldsymbol{x}(t_0)|| = \sum_{1 \le i,j \le n} |X_{ij}^t - X_{ij}^{t_0}|,$   
 $P_s = \sum_{i=1}^n \rho_s(\boldsymbol{x}(t), i), \text{ for } s \in [1, L].$ 



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The moment equations are

$$egin{aligned} & E[C(oldsymbol{x}(T_1, \hat{oldsymbol{ heta}})) | oldsymbol{x}(t_0), oldsymbol{
ho}] = c^{obs}, \ & E[oldsymbol{P}(oldsymbol{x}(T_1, \hat{oldsymbol{ heta}})) | oldsymbol{x}(t_0), oldsymbol{
ho}] = oldsymbol{p}^{obs}. \end{aligned}$$



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## **Conditional Moment Estimation**

$$E[C(\boldsymbol{x}(T_1, \hat{\boldsymbol{\theta}}))|\boldsymbol{x}(t_0), \boldsymbol{\rho}] = c^{obs} = ||\boldsymbol{x}(t_1) - \boldsymbol{x}(t_0)||.$$

The expected number of changes in the simulated network must be equal to the number of changes in the observed network (from initial network).

Impose the following:  $T_1 = \min\{t | C(t) \ge c^{obs}\}$ . Moment equation is

$$E[P(\mathbf{x}(T_1, \hat{\boldsymbol{\beta}})) | \mathbf{x}(t_0), \rho, C] = \boldsymbol{p}^{obs}.$$

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### **Stochastic Approximation**

Snidjers uses an updated version of the Robbins-Monro [1951] method to iteratively update the parameters

$$\hat{oldsymbol{eta}}_{N+1}=\hat{oldsymbol{eta}}_N-a_ND_0^{-1}(oldsymbol{P}_N-oldsymbol{p}^{obs})$$

where N is the step in the CTMP,  $a_N$  is a series that slowly converges to 0 with rate  $N^{-c}$  (0.5 < c < 1) and  $D_0$  is the diagonal matrix with entries:  $D_{\hat{\beta}_t} = \frac{\partial E[\mathbf{P}]}{\partial \hat{\beta}_t}$  on the diagonal.



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Optimal convergence:

• Polyak [1996]: when  $D_0$  has positive real eigenvalues and  $\hat{\beta}_N$  generated by average of consecutive values.

To have good convergence for relatively low N:

- Pflug [1990] showed  $P_N p^{obs}$  negative.
- If  $(P_N p^{obs})'(P_{N-1} p^{obs})$  positive then drifting toward limit point and  $a_N$  remains constant.

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## MCMC

- Phase I: approximate  $D_0$  using common random numbers.
- Phase II: subphases κ with constant a<sub>N</sub>. Bounded by positive successive products and steps, (n<sup>-</sup><sub>2κ</sub>, n<sup>+</sup><sub>2κ</sub>), so that N<sup>3/4</sup>a<sub>N</sub> tends to positive finite limit. At the end of each subphase the average estimate is used as input for next subphase. β̂<sub>N</sub> over last subphase is used as final output β̂.
- Phase III: Given  $\hat{\beta}$  estimate  $cov(\hat{\beta}) \approx D_{\hat{\beta}}^{-1} \Sigma_{\hat{\beta}} D_{\hat{\beta}}'^{-1}$ . 1000 networks generated:  $\mathbf{x}(T_1, \hat{\beta})$ .



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## 2016/17 Structured MSc Social Network



Figure: AIMS Network, December,  $\mathbf{x}(t_0)$  (left) and April,  $\mathbf{x}(t_1)$  (right) The size of each node is proportional to in-degree. The shape of the node represents the actors sex, and the colour of nodes represent counter

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## 2016/17 Structured MSc Social Network

#### Table: Network Topologies for AIMS Network

	December	April
Number of Nodes	41	41
Number of Edges	212	203
Density	0.13	0.12
Average Degree	5.17	4.95
Reciprocity	0.58	0.58
Transitiviy	0.30	0.39
Distance	2.58	2.96

The network has changed by a total of c = 169 ties. Jaccard coefficient

$$\frac{N_{11}}{N_{11}+N_{01}+N_{10}}=0.4$$



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## Model Implementation

#### Table: Parameter Estimation of Friendship Evolution for AIMS Network.

		Model I			Model II			Model III				
Network Effects	Estimate	S.E	p-value	Conv.	Estimate	S.E	p-value	Conv.	Estimate	S.E	p-value	Conv.
				t-ratio				t-ratio				t-ratio
0 Rate parameter	7.61	(0.85)			7.70	(0.86)			7.69	(0.88)		
1 . eval outdegree (density)	-1.40	(0.24)	3.66e-09	-0.04	-1.33	(0.17)	1.71e-15	0.02	-1.26	(0.18)	5.46e-12	-0.04
2 . eval reciprocity	1.38	(0.22)	7.12e-10	-0.01	1.32	(0.19)	1.18e-11	0.05	1.30	(0.21)	2.99e-10	-0.02
3 . eval transitive triplets	0.21	(0.08)	0.01	-0.02	0.18	(0.05)	5.37e-04	0.03	0.17	(0.05)	6.99e-04	-0.07
4 . eval 3-cycles	-0.03	(0.13)	0.79	0.02								
5 . eval transitive ties	-0.04	(0.23)	0.88	-0.01								
6 . eval balance	0.04	(0.02)	0.03	0.03	0.04	(0.02)	0.03	-0.01	0.05	(0.02)	0.01	0.06
7. eval number of actors at dist	ance 2 -0.27	(0.07)	1.10e-3	-0.03	-0.27	(0.07)	1.10e-04	-0.03	-0.29	(0.07)	4.68e-05	-0.03
10 . eval same country	0.58	(0.24)	0.01	-0.01	0.57	(0.23)	0.01	0.01	0.54	(0.24)	0.03	0.03
11. eval sex alter	0.20	(0.16)	0.18	0.07								
12. eval sex ego	0.04	(0.16)	0.81	0.06								
13. eval same sex	0.05	(0.17)	0.76	-0.03								



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#### **Network** Topology



#### Table: Local network metrics, $\gamma_r(\mathbf{x}, i)$ .



## Method of Moments

$$P_s = \sum_{i=1}^n \rho_s(\mathbf{x}(T_1), i), \text{ for } s \in [1, L].$$

Table:  $P_s$  and  $p_s$  statistics for network effects,  $\rho_s$ , for Model III

Effect	$ ho_{s}$	Target <i>p₅</i>	Mean Estimate <i>Ps</i>
Out-degree	$ ho_1$	203	202
Reciprocity	$ ho_{3}$	118	118
Transitive triplets	$ ho_{ extsf{4}}$	360	355
Number Distance 2	$ ho_{6}$	429	429
Balance	$ ho_{8}$	399	405
Same country	$ ho_{15}^{country}$	65	65
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## Network Difference: $\mu_q$





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# Network Difference: $\gamma_q$



Figure 5.4: Violin Plots for difference metrics,  $\gamma_r$ , red dots are  $\gamma^{obs}$  and green dots are  $\gamma^{median}$ . The blue shaded region (violin) represents the sample data for each variable. In-degree and out-degree show cumulative degree distribution. The width of the violin is proportional to the density and the length is proportional to the range. Symmetry of the data is indicated by symmetrical violins on the horizontal and vertical axis.



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#### **Research** Questions

- How do well-known principles of network formation, namely reciprocity, popularity, and triadic closure, vary in importance throughout the network formation period as the structure itself evolves? (Schaefer, Light, Fabes, Hanish, & Martin, 2010)
- How does peer influence on smoking cessation differ in magnitude from peer influence on smoking initiation? (Haas & Schaefer, 2014)
- What drives collaboration among collective actors involved in climate mitigation policy? (Ingold & Fischer, 2014)
- Why are some more peer than others? evidence from a longitudinal study of social networks and individual academic performance. (Lomi, Snijders, Steglich & Torló, 2011)

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## **Model Limitations**

- Markovian, one tie change...
- Constant effects for more than two observations.
- Closed group study.
- Expensive data collection.
- Accuracy and reliability inference.
- $\implies$  Online social networks.



